

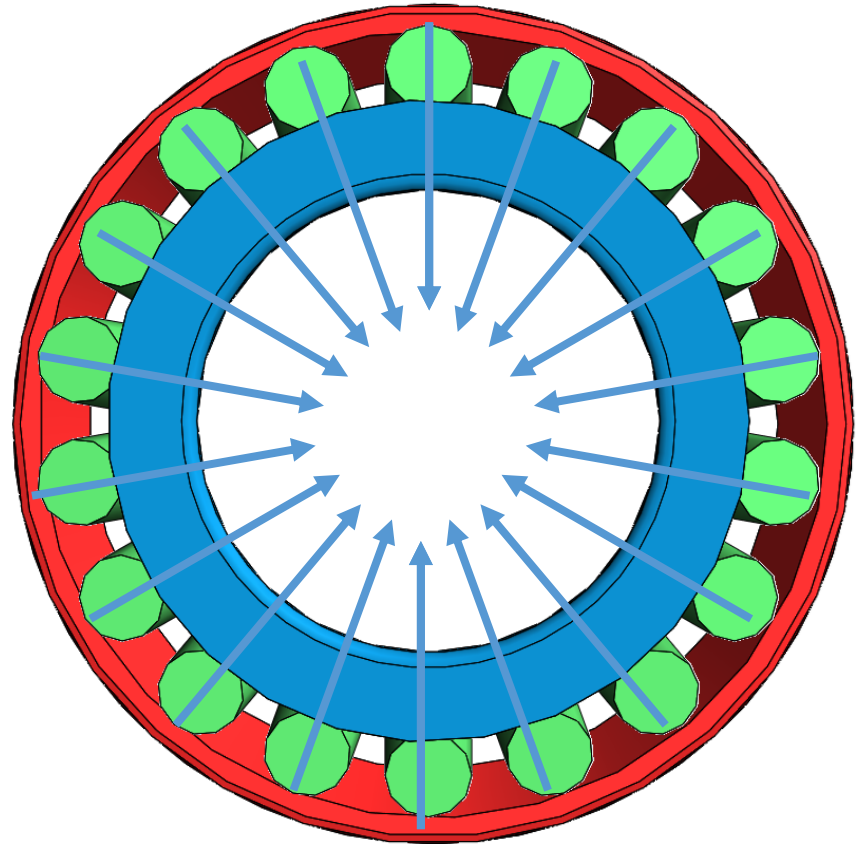
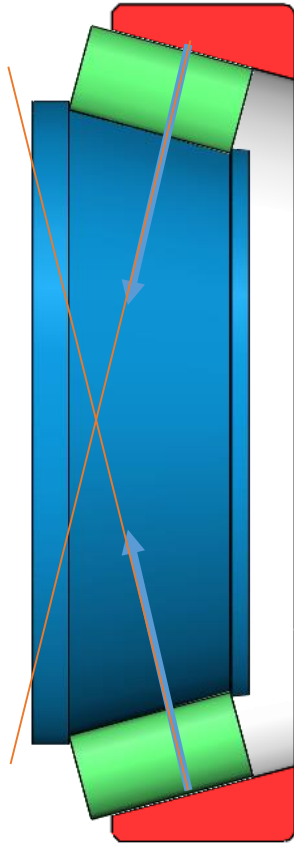
# Design and size angular contact bearing arrangements



# **Angular contact bearings**

## **General description**

# Architecture of angular contact bearings

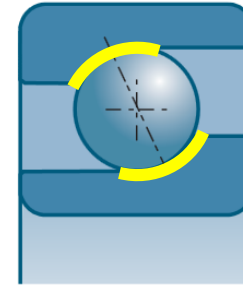


Load support on a cone, unilateral actions → axial load transmitted in a **single direction**, determined by mounting

# Angular contact bearings

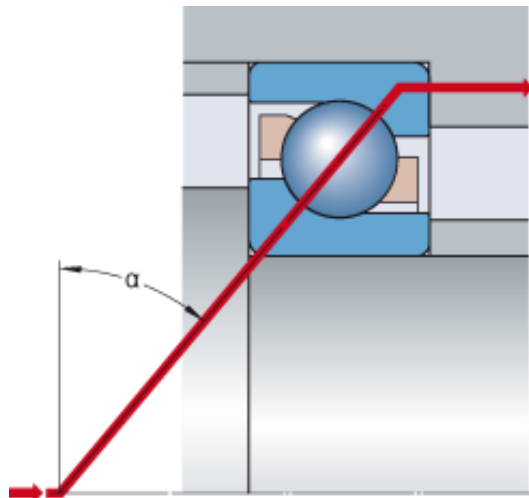
raceways

Gap between the two raceways

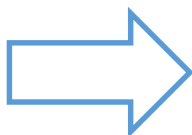


**Contact angle = angle between the load direction (between the 2 contact points) and the radial direction**

- Typical bearing:  $\alpha = 40^\circ$
- Precision bearing:  $\alpha = 15^\circ$  ou  $25^\circ$



Contact angle

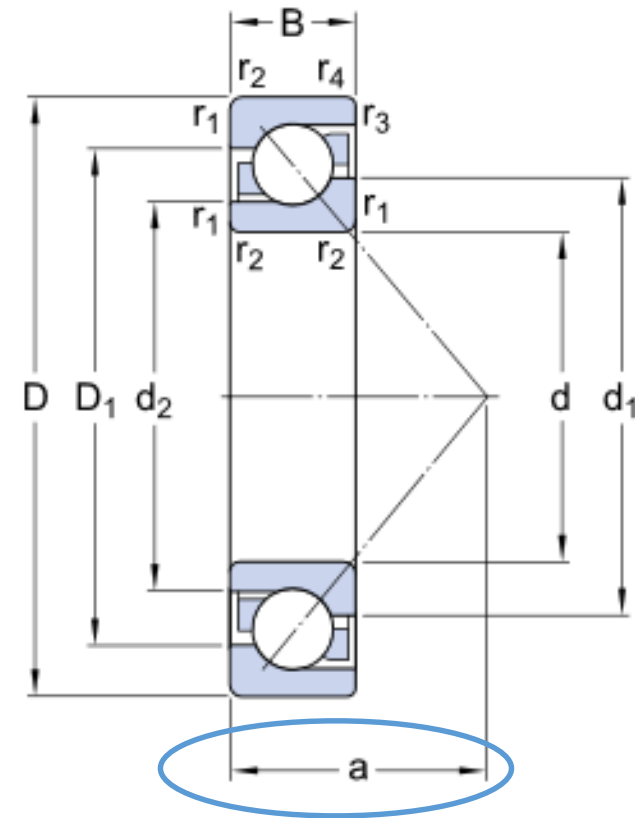


- ✓ Support axial loads
- ✓ Axial load in a single direction
- ✓ Equivalent to a unilateral spherical joint

# Angular contact ball bearings

## Characteristics

- Mounted by pairs in opposition
- Rings cannot be separated
- Large number of balls → large load capacity
- Axial load increases with loading angle
- Permissible misalignment: 1 to 2'



## Applications

- Vertical axis electrical engines
- Car front wheels ...

# Tapered roller bearings

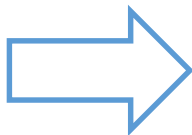
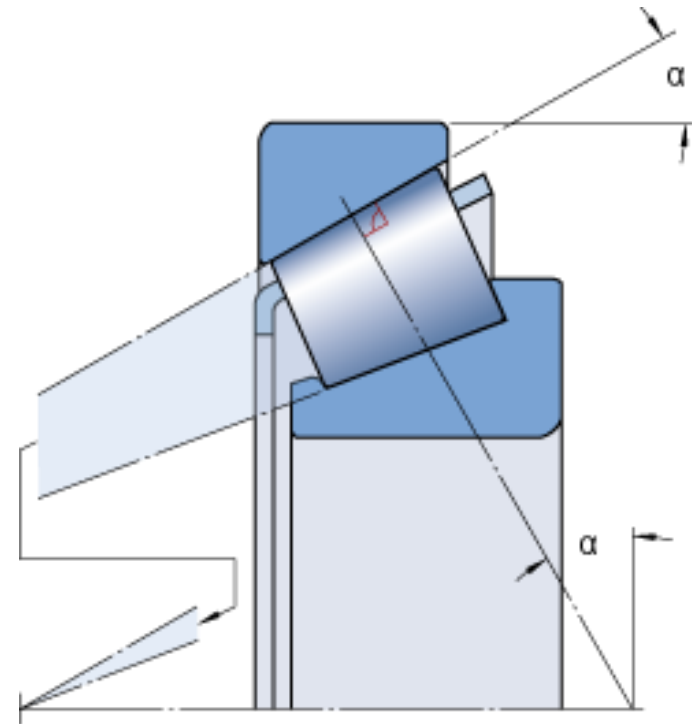
## Description

Rollers and raceways are cone portions

Rollers and raceways are slightly rounded

All cones have the same apex to ensure rolling and limit sliding

Linear contact



- ✓ Designed for combined loads
- ✓ Axial force transmission on a single direction
- ✓ Equivalent to a unilateral spherical joint

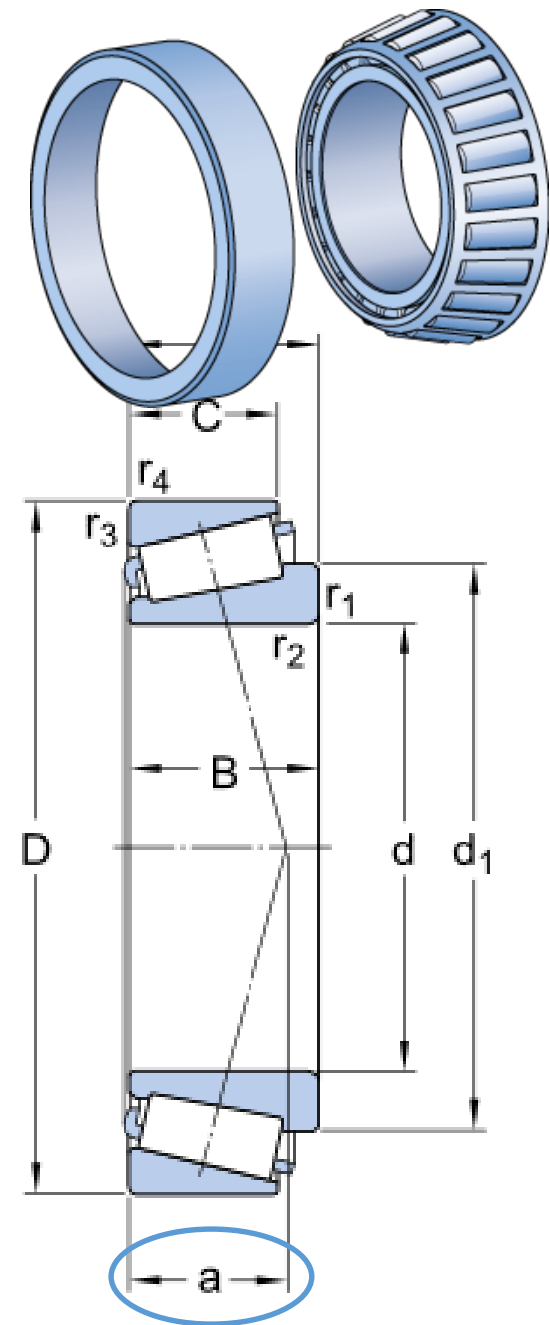
# Roulement à rouleaux coniques

## Characteristics

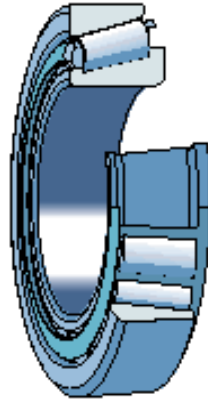
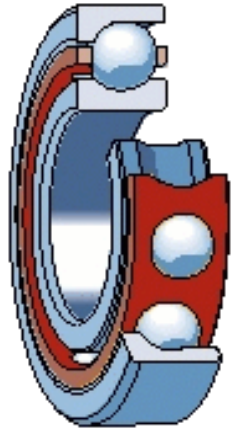
- Mounted by pairs in opposition
- Rings can be separated
- Linear contact → large load capacity
- Load capacity increases with loading angle
- Permissible misalignment: 1 to 4'
- Shaft and housing must be really coaxial

## Applications

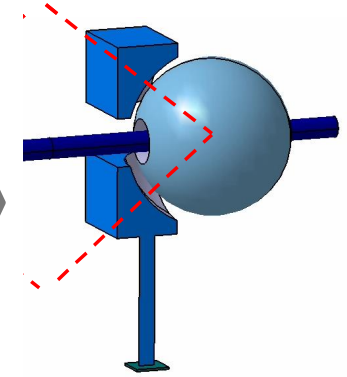
- Car back wheels
- Reducers ...



# Mounting



1 complete rotation + 2 limited rotations (permissible misalignment) + axial locating in a single direction

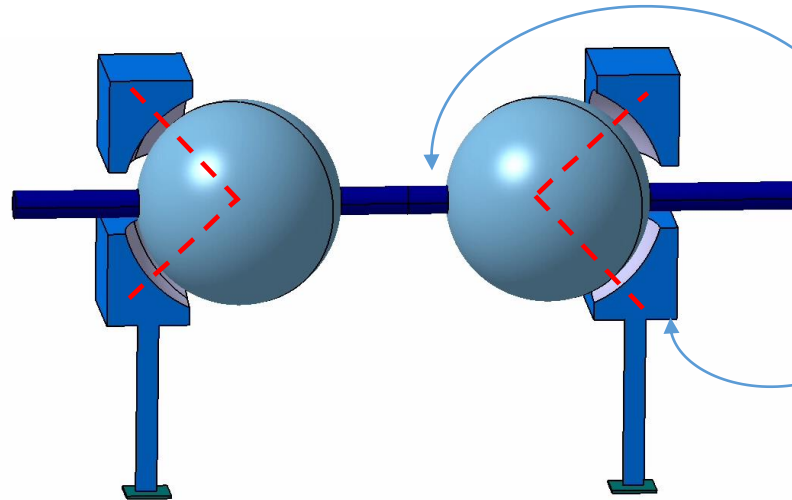


« Half » spherical joint



# Revolute joint

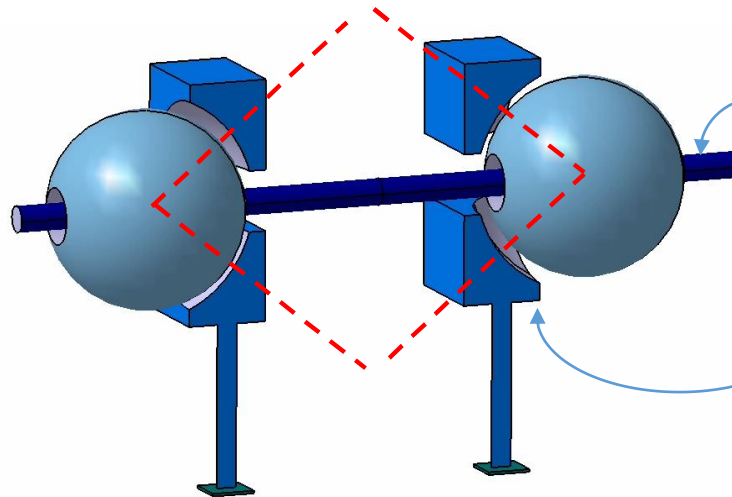
X mounting =  
face-to-face  
mounting  
Load centers are  
closer  
Shaft is more rigid



Locating:

- Inside on the shaft
- Outside in the housing

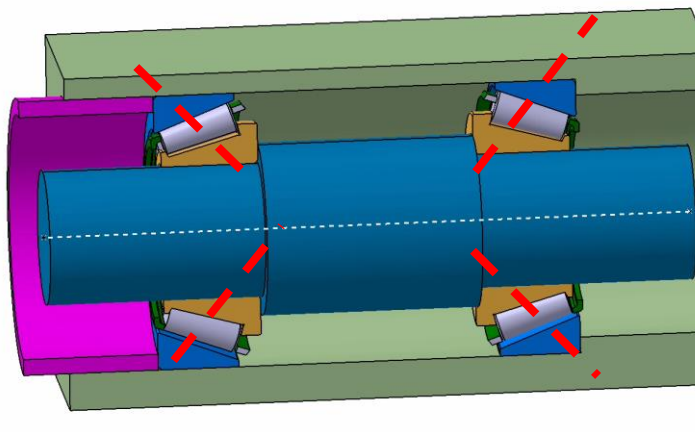
O mounting =  
back-to-back:  
Load centers  
are distant  
Assembly is  
more robust to  
external radial  
forces



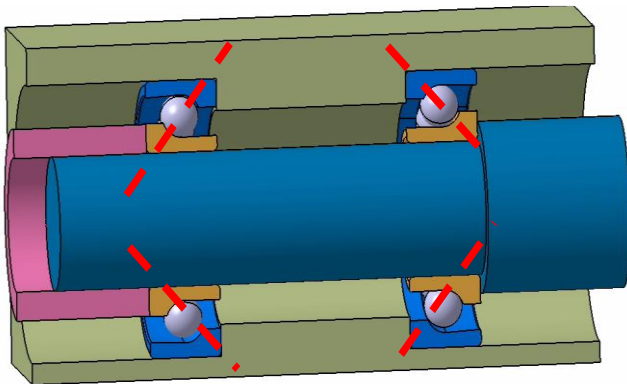
Locating

- Outside on the shaft
- Inside in the housing

## Consequences on mounting

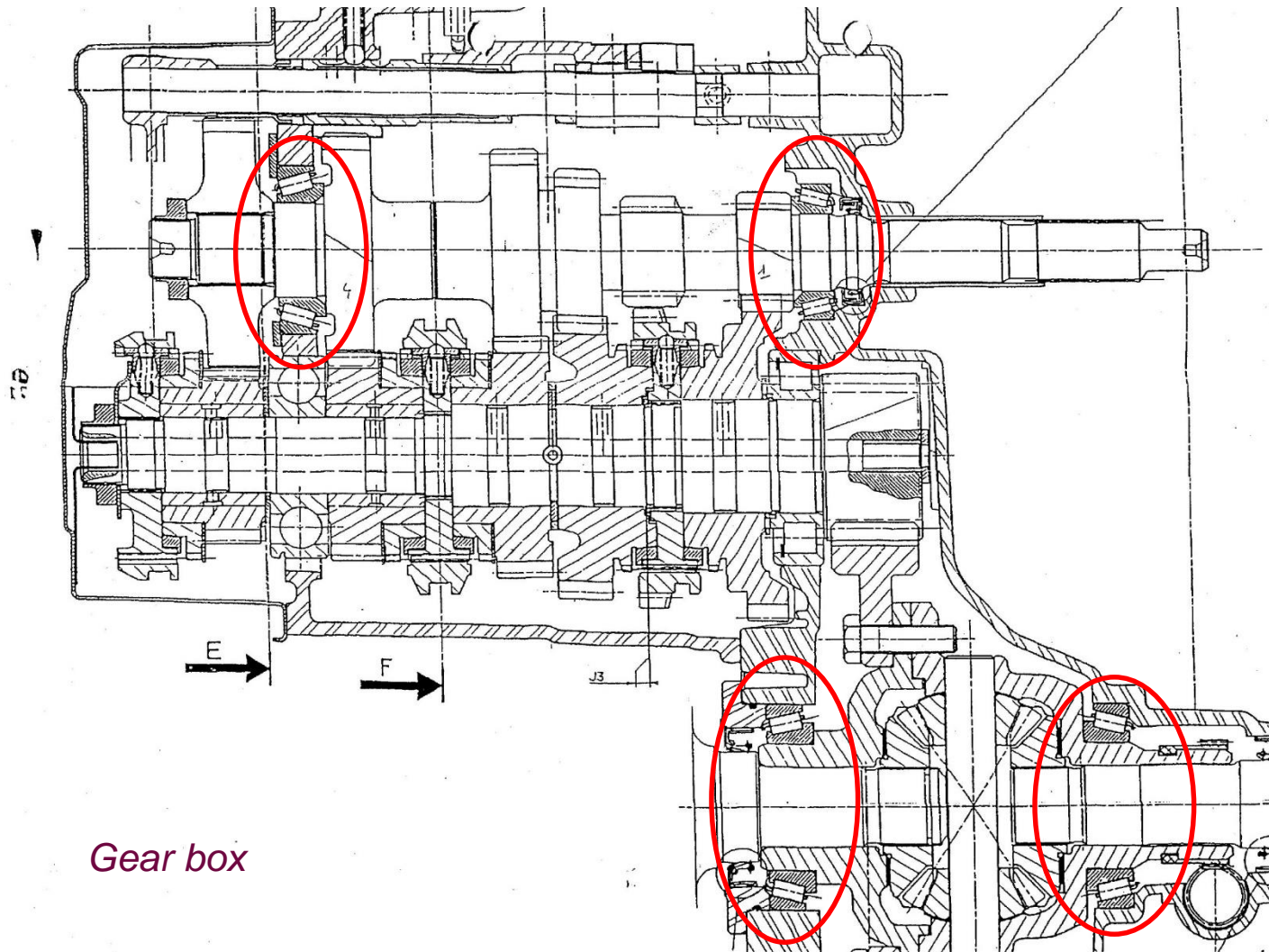


- Internal (inside) locating preferably by a shoulder
- Rings with interference fits preferably mounted on shoulders



- X mounting (face to face) better when shafts rotates with respect to the load direction
- O mounting (back to back) better when housing rotates with respect to the load direction

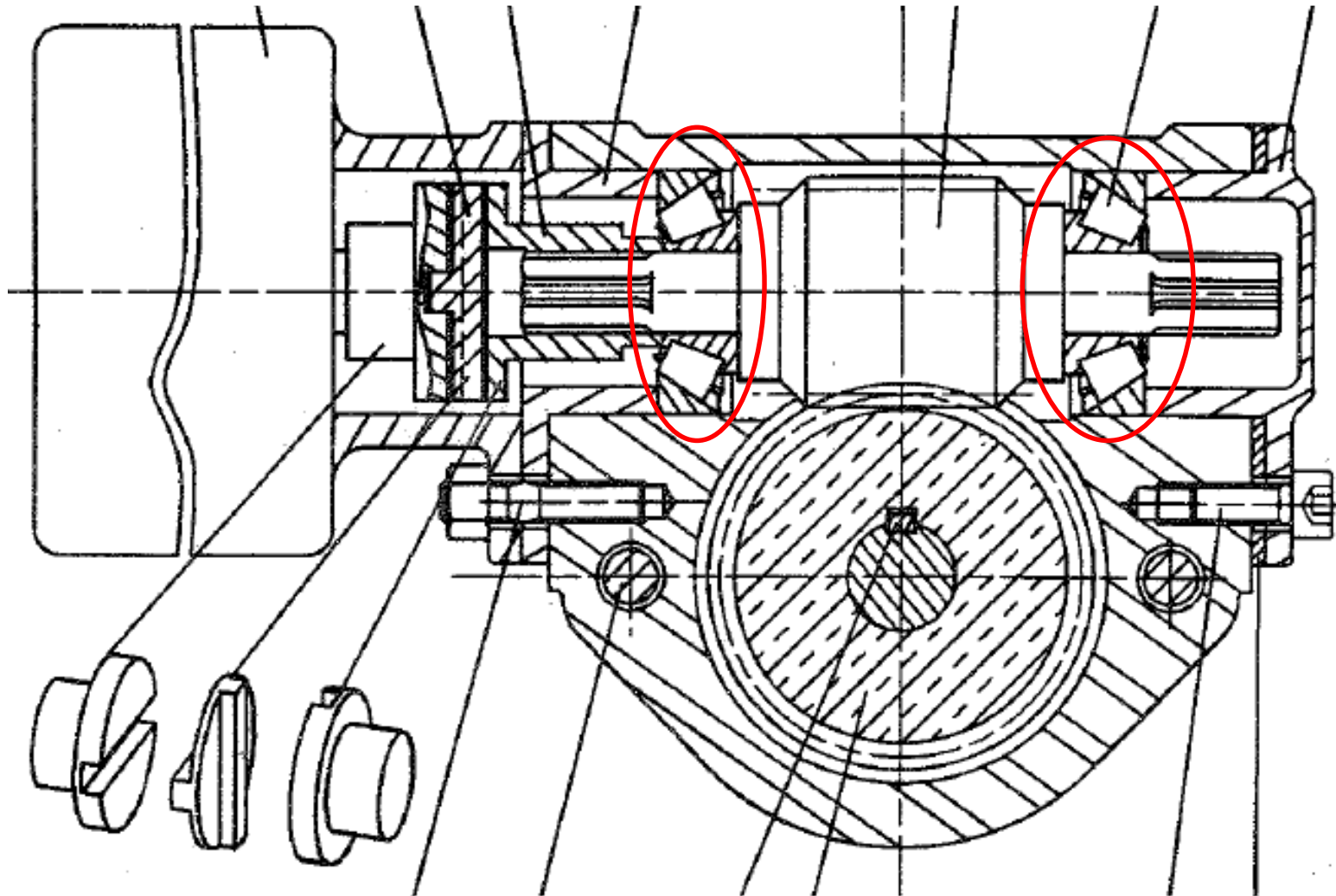
# Examples



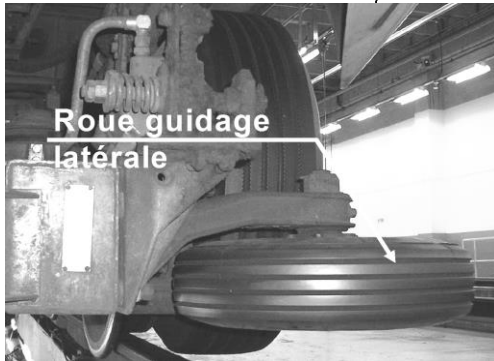
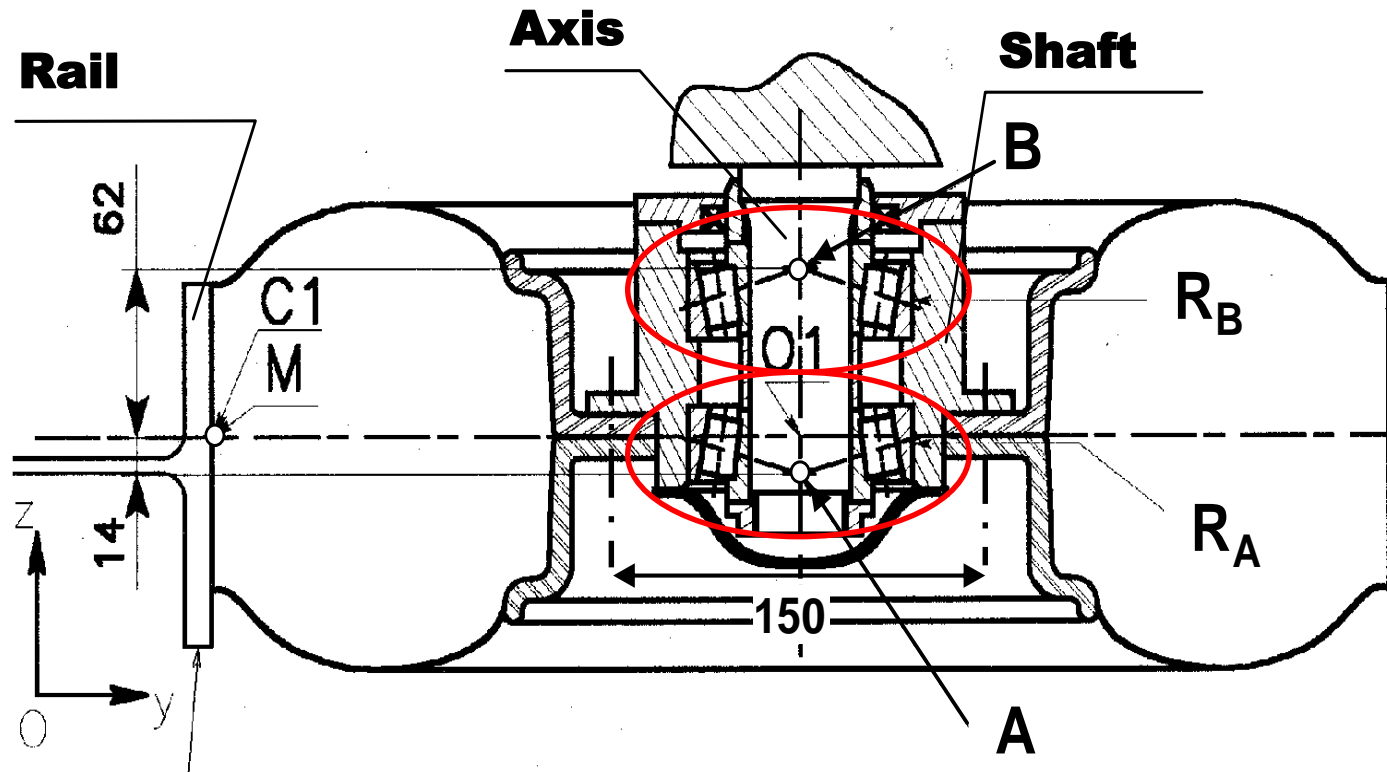
*Gear box*

# Examples

## *Electrical linear actuator*

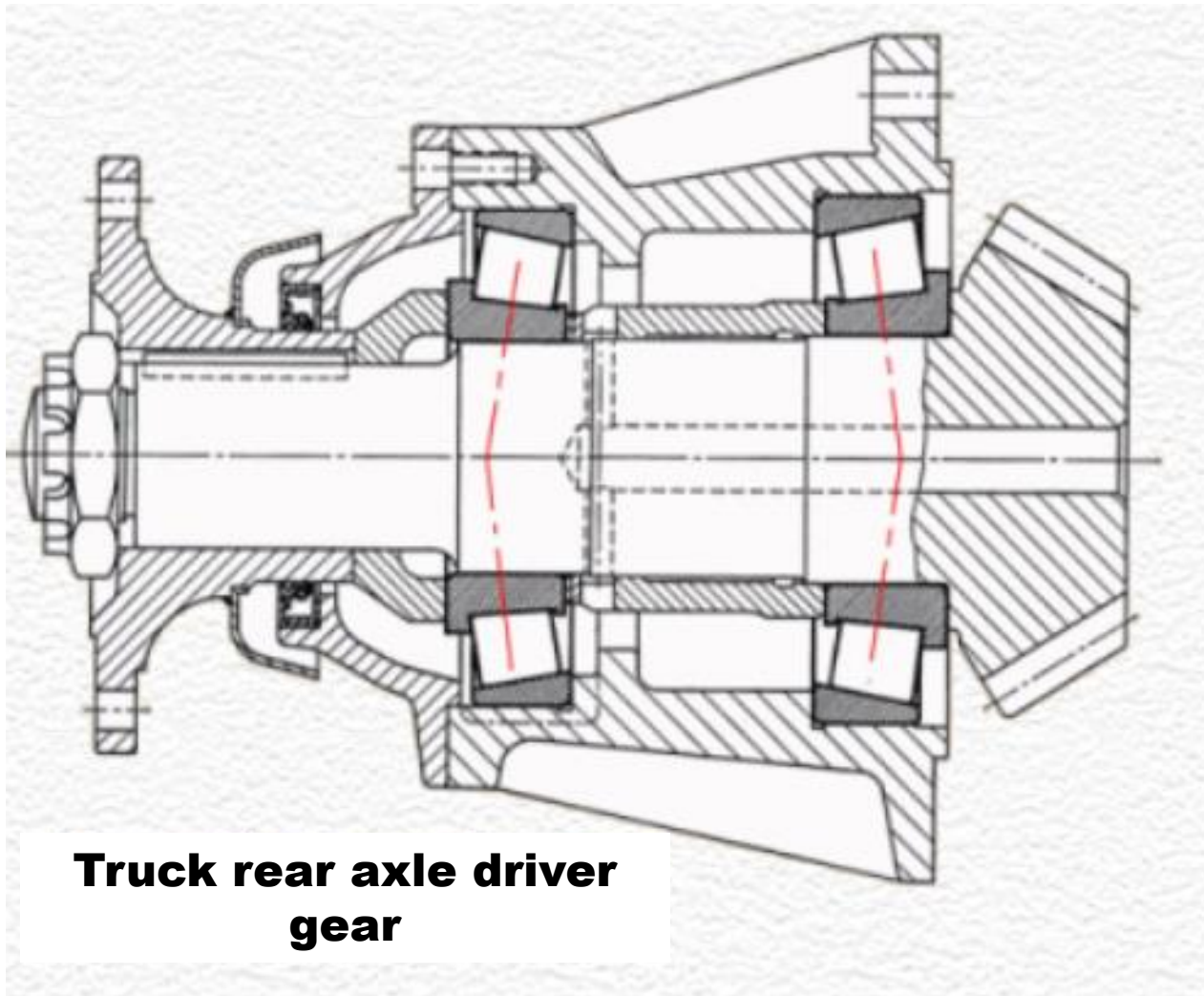


# Examples



*Guiding wheel for the subway*

# Examples

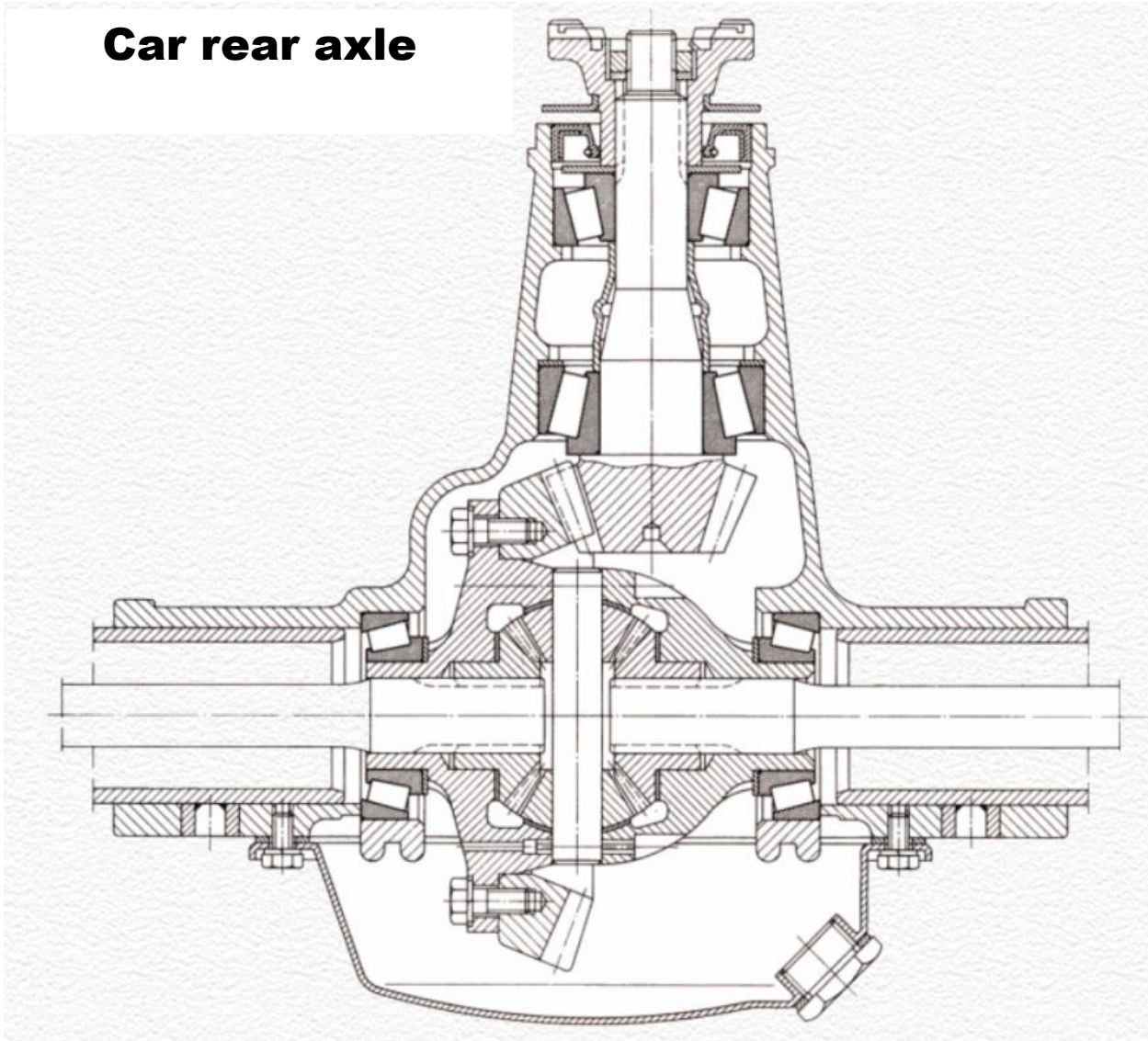


**Truck rear axle driver gear**

<http://barreau.matthieu.free.fr/cours/Liaison-pivot/pages/roulements-2.html>

# Examples

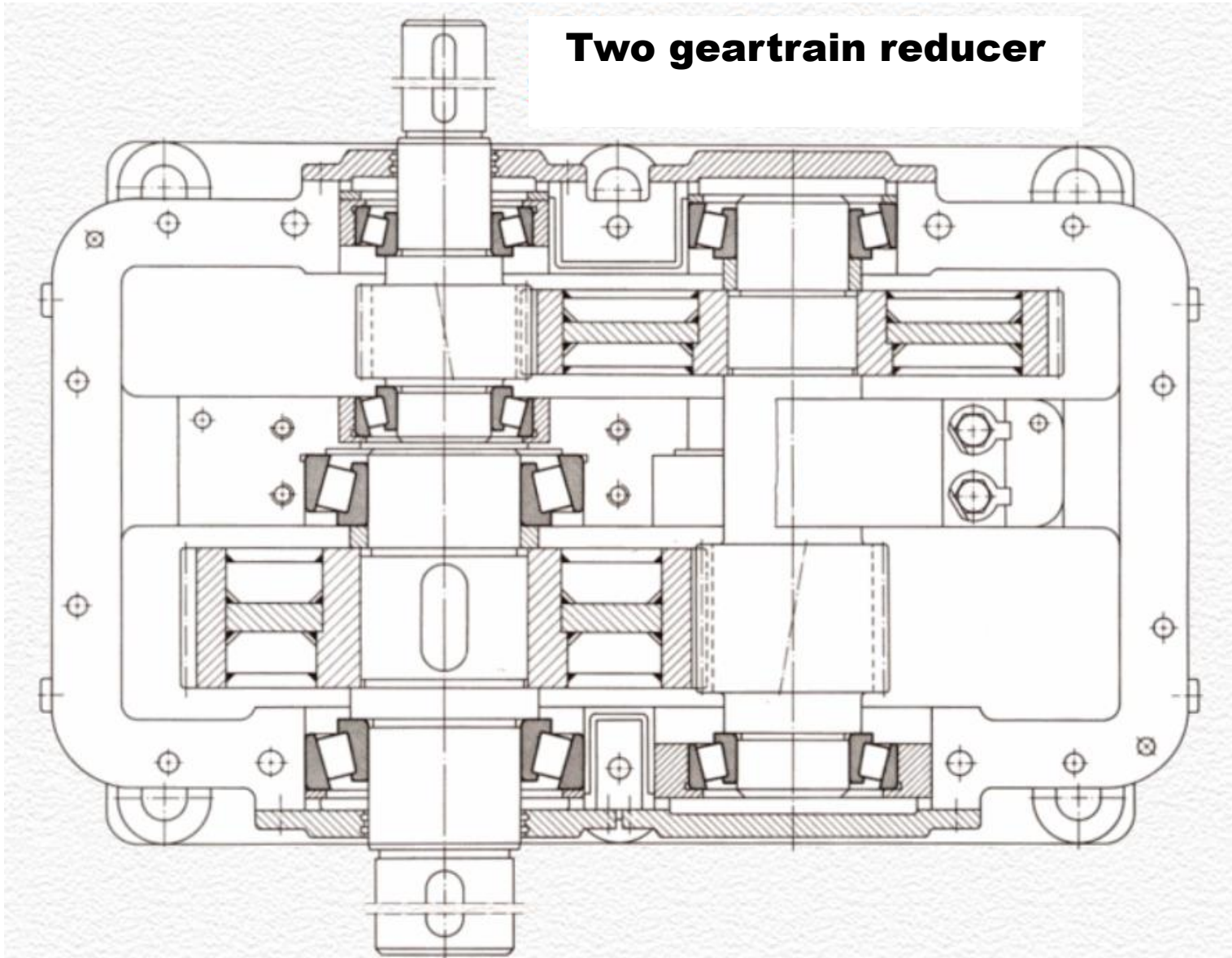
## Car rear axle



<http://barreau.matthieu.free.fr/cours/Liaison-pivot/pages/roulements-2.html>

# Examples

## Two geartrain reducer

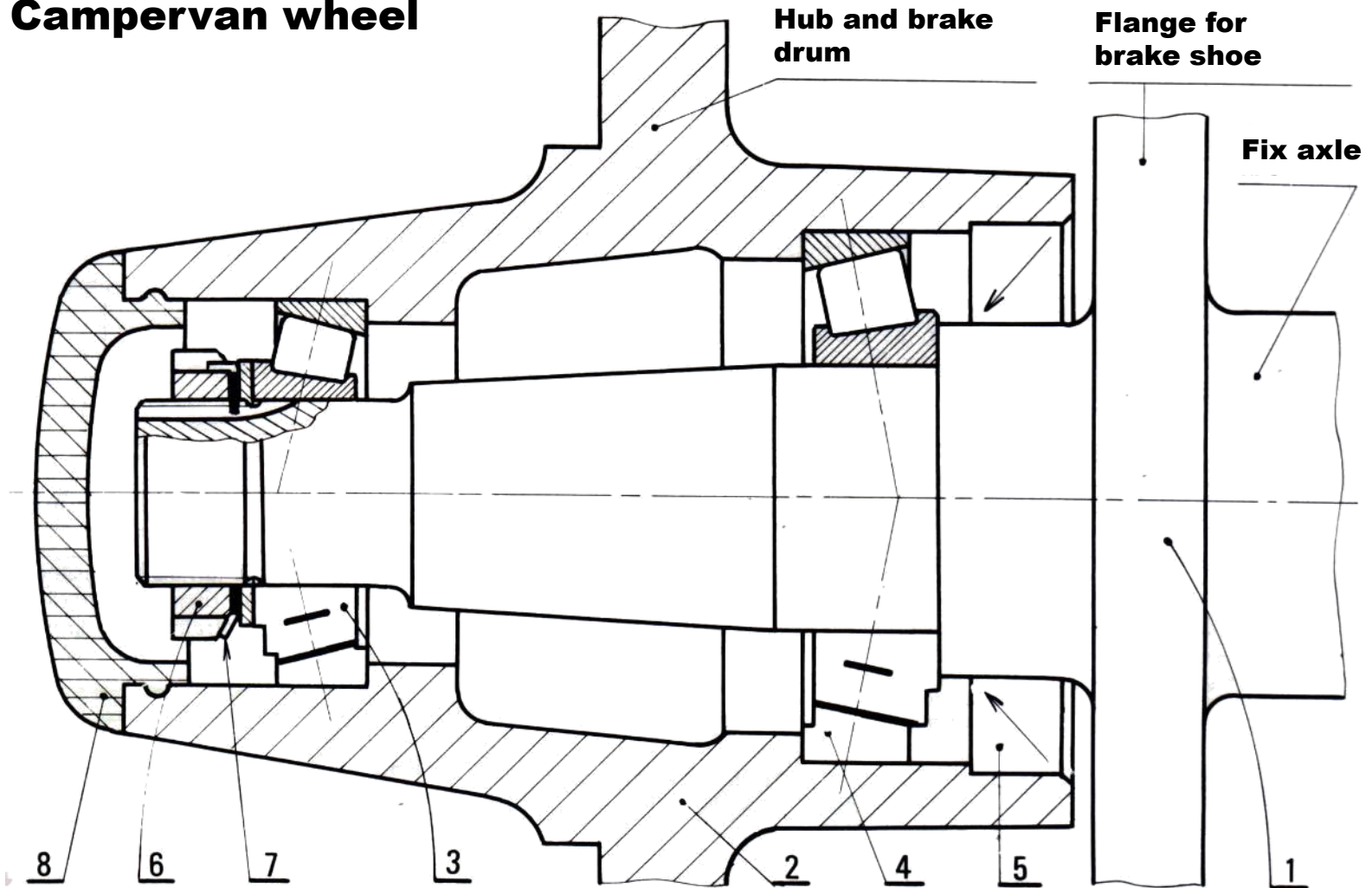


<http://barreau.matthieu.free.fr/cours/Liaison-pivot/pages/roulements-2.html>



# Examples

## Campervan wheel

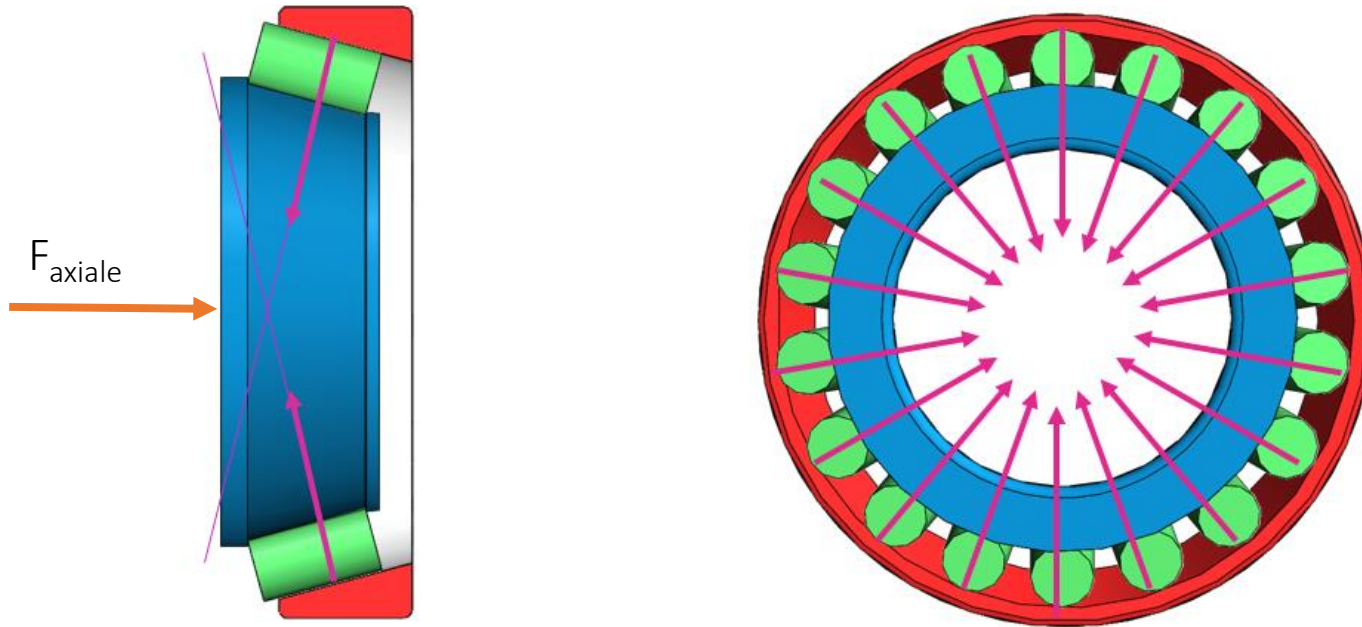




# **Loading angular contact bearings**

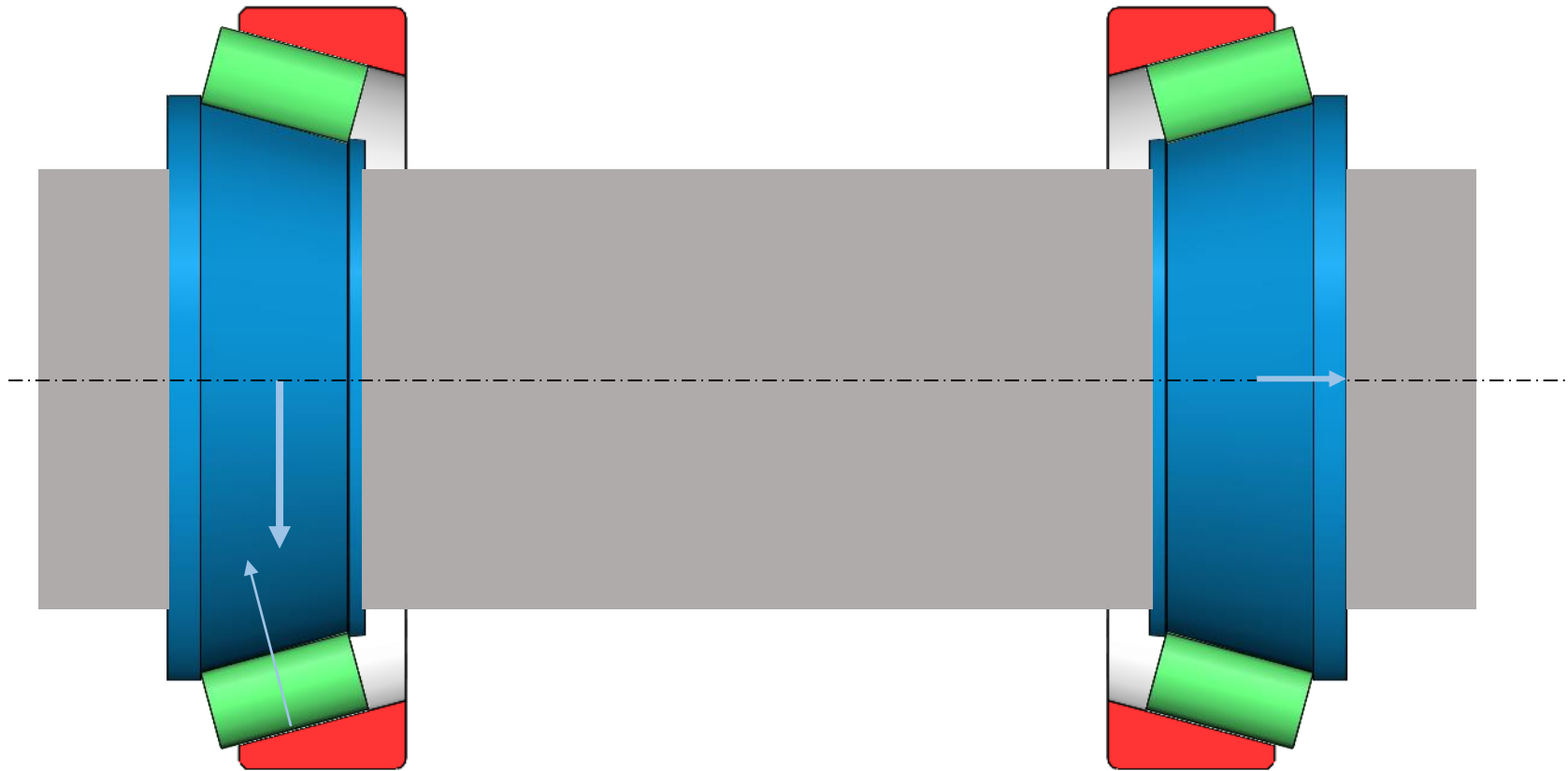
# Axial load

## Contact loads on a cone



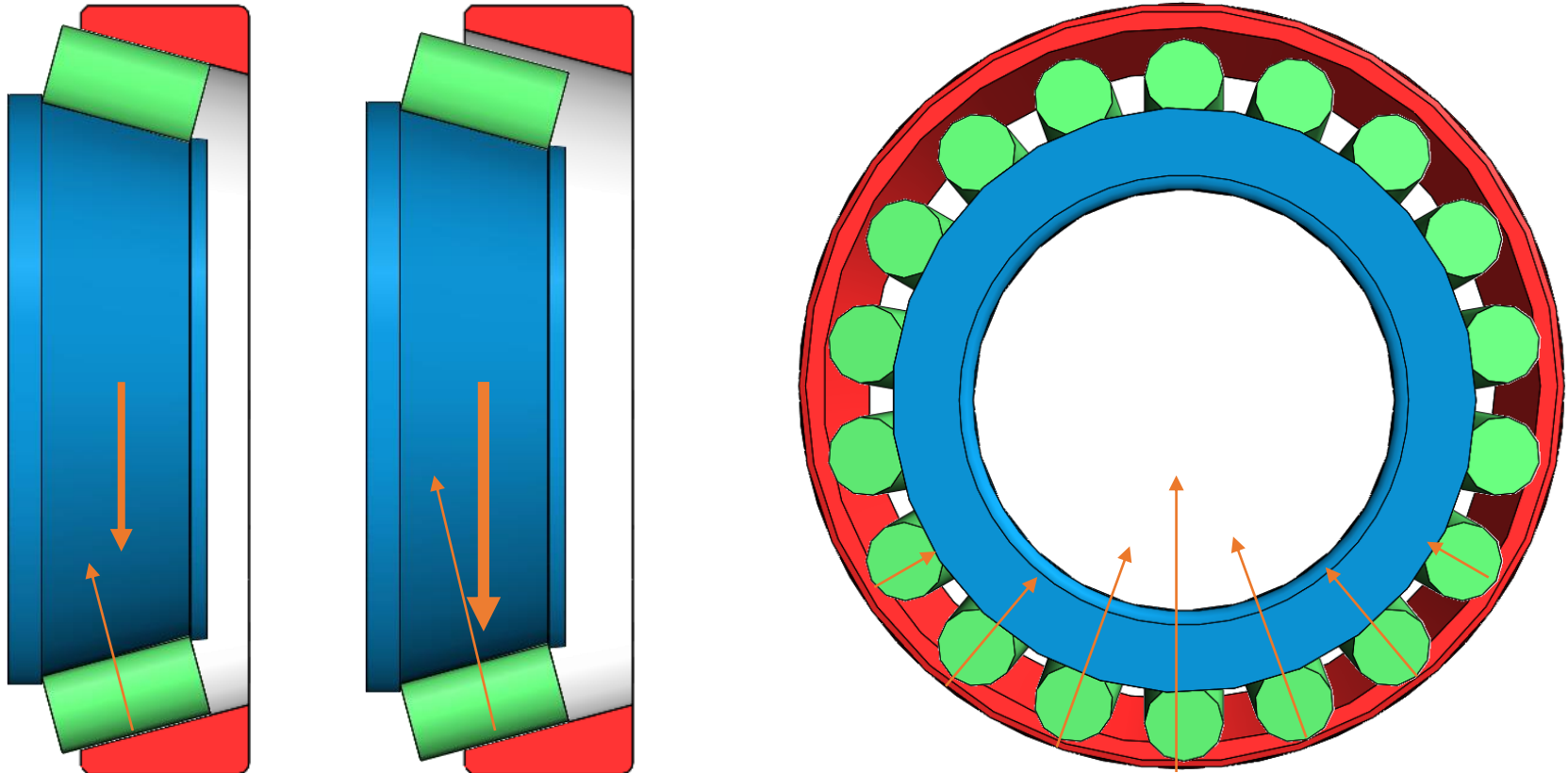
Axial load equally distributed on all rolling elements  
Inner ring comes closer to the outer ring

## Radial load



Radial load only supported by rolling elements placed along the loading direction  
Axial equilibrium requires the presence of the second bearing mounted in the opposite direction.

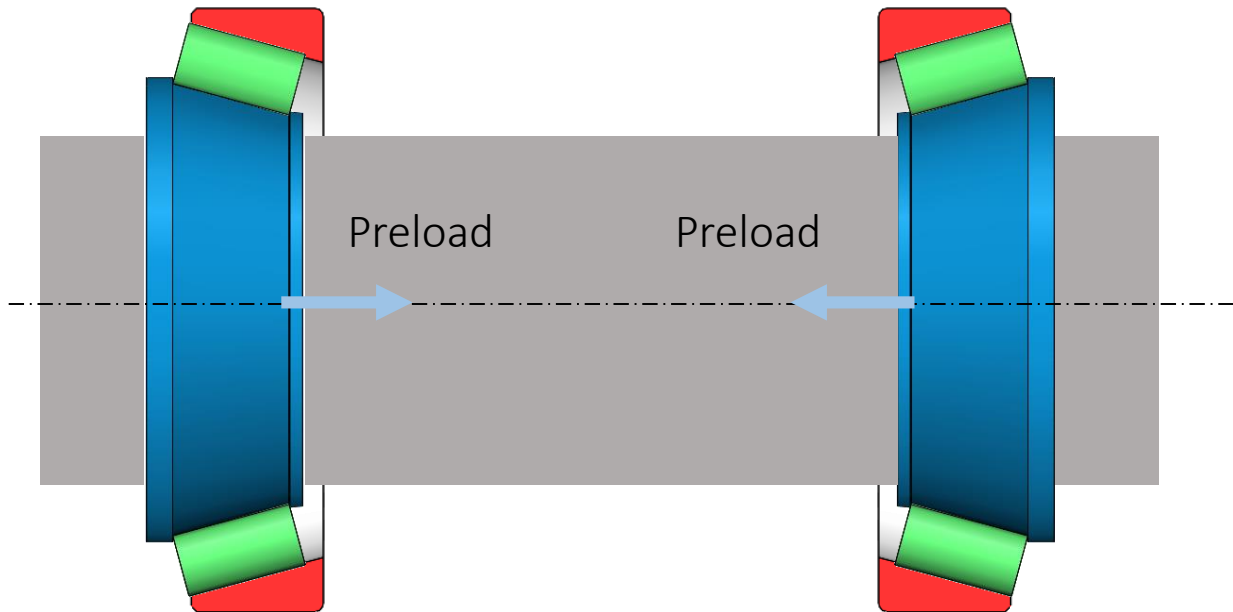
## Radial load



Radial load puts apart inner ring from outer ring → fewer and fewer rolling elements support the load → higher and higher load on those rolling elements

## Preload: condition for a good functioning

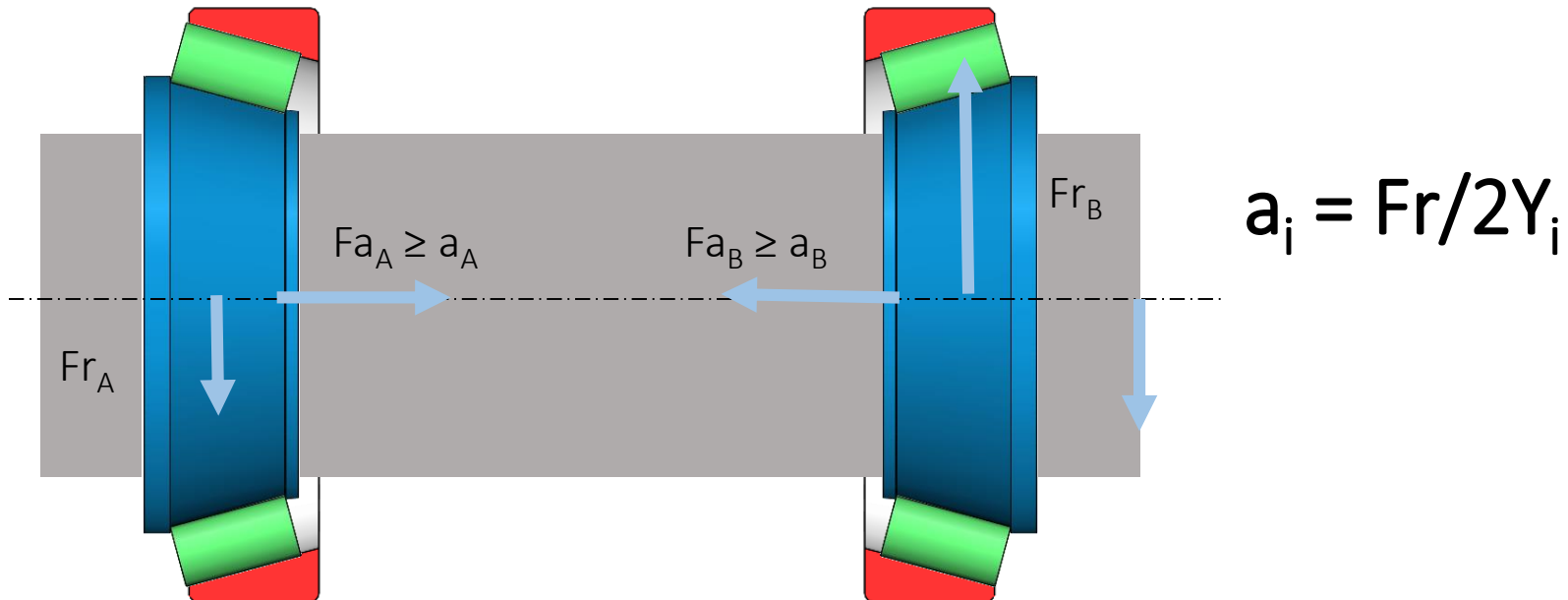
At least half of the rolling elements should support the load



Mounting condition: create an axial preload to bring inner and outer rings closer and increase the number of rolling elements to support the load.

## Preload: condition for a good functioning

Preload must ensure that axial load on a bearing is higher than the induced axial load  $a_i$  due to external radial load and geometry



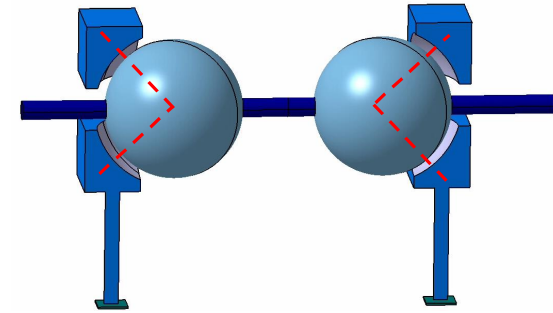
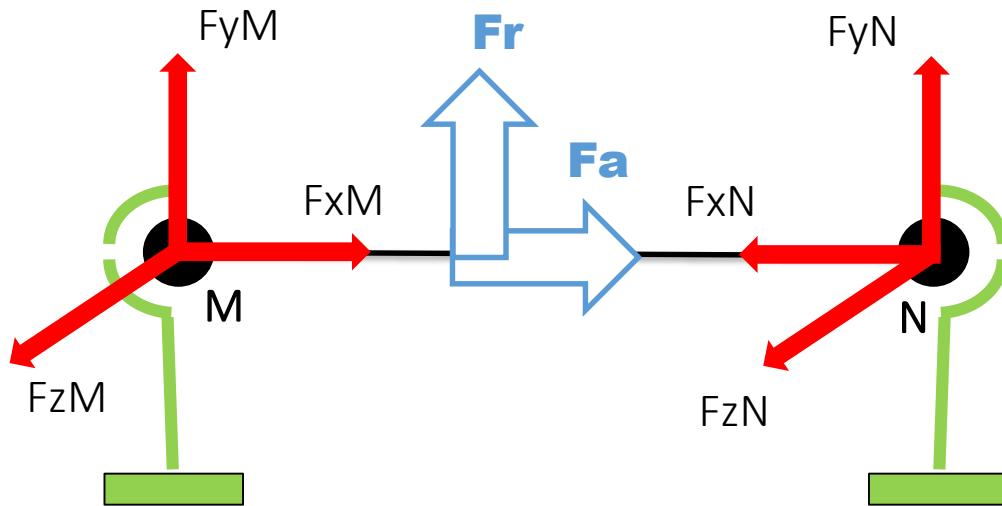
Induced axial load corresponds to the minimum load for half of the rolling elements to be loaded.



# **Sizing of angular contact bearings**



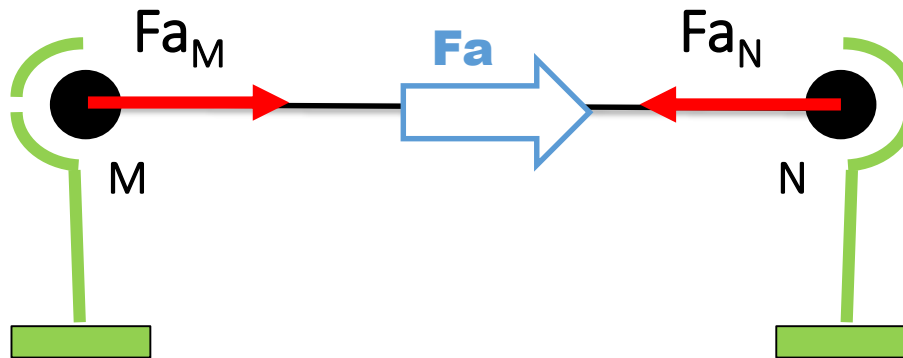
# Static equilibrium



Static equilibrium of the shaft  $\rightarrow$  determine radial loads in bearings ( $F_y$  and  $F_z$ ) BUT NOT the axial loads ( $F_x$ )

## AXIAL static equilibrium

For sizing, we **assume** that axial load is supported by one bearing and the other supports only the induced axial load.

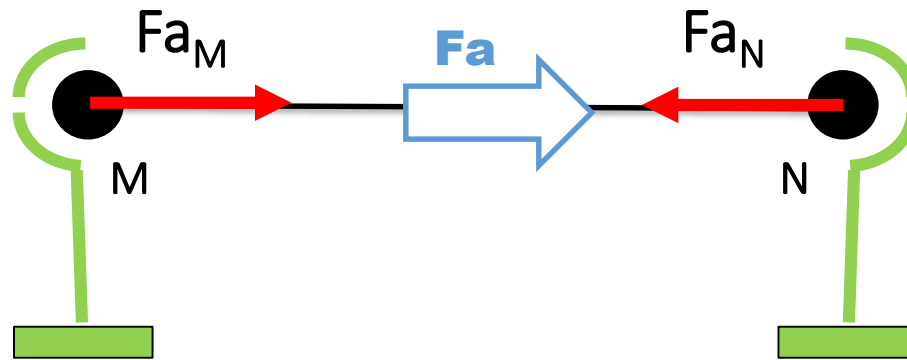


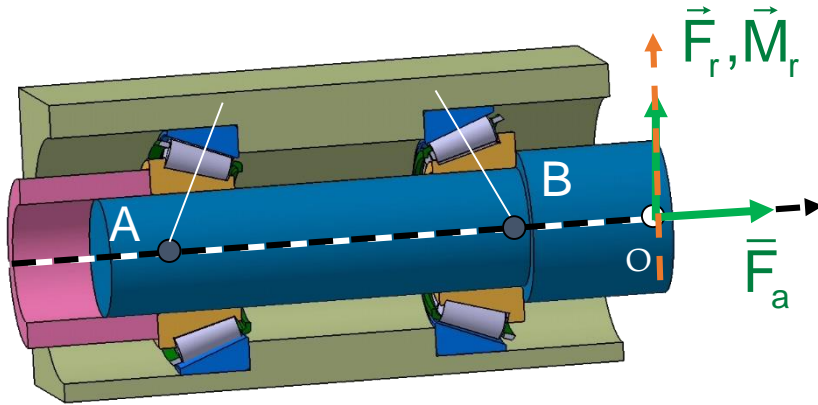
Axial equilibrium:

$$+F_{a_M} - F_{a_N} + F_a = 0 \text{ with}$$
$$F_{a_M} = a_M \text{ et } F_{a_N} \geq a_N \text{ OR } F_{a_M} \geq a_M \text{ et } F_{a_N} = a_N$$

# Équilibre statique AXIAL du montage

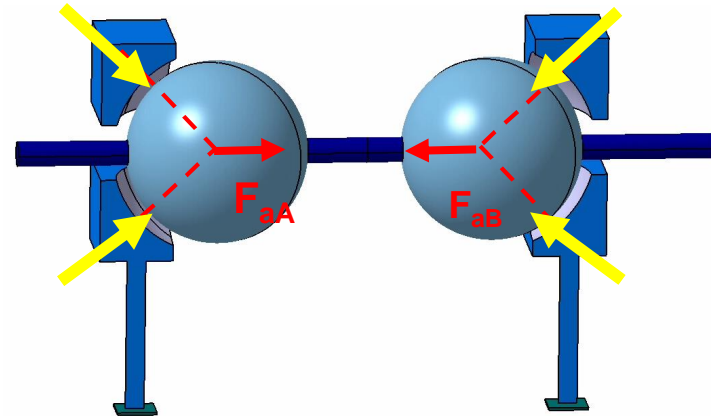
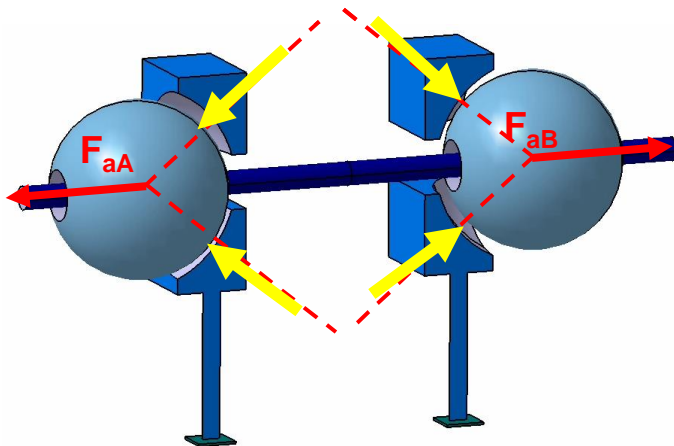
How to determine which bearing supports only its induced axial load ?



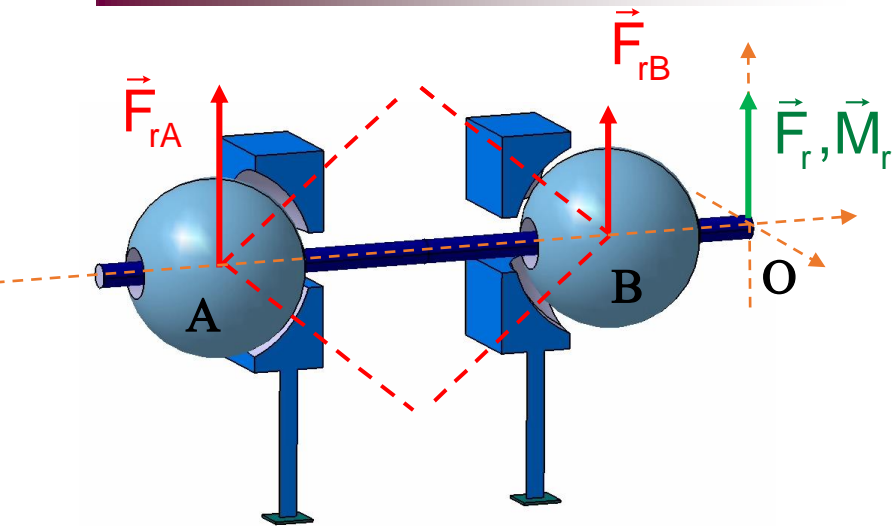


Identify external loads on the shaft  
Locate the load centers A and B

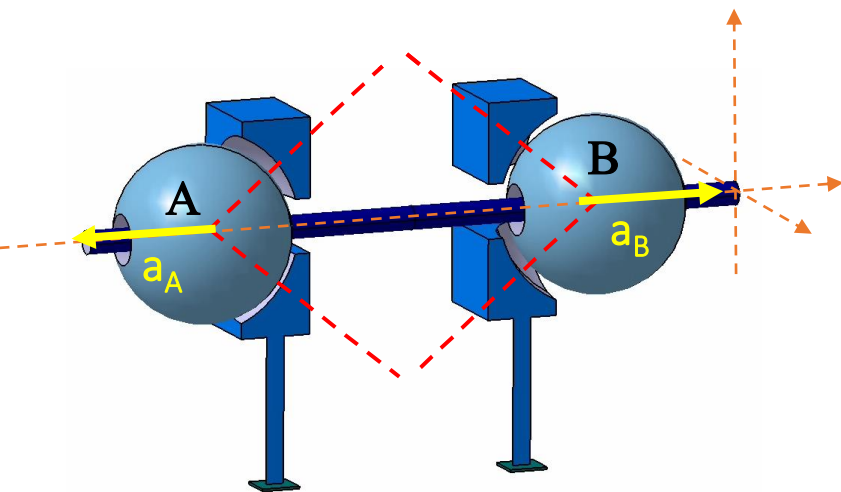
Identify the direction of the load exerted by bearings on the shaft



## Calculation of axial loads



Loads in bearings are applied at the load center



Write the radial static equilibrium:

$$\vec{F}_r + \vec{F}_{rA} + \vec{F}_{rB} = \vec{0}$$

$$\vec{M}_r + \vec{AO} \wedge \vec{F}_r + \vec{AB} \wedge \vec{F}_{rB} = \vec{0}$$

Deduce the norm of radial loads in the bearings:

$$R_A = |\vec{F}_{rA}|$$

$$R_B = |\vec{F}_{rB}|$$

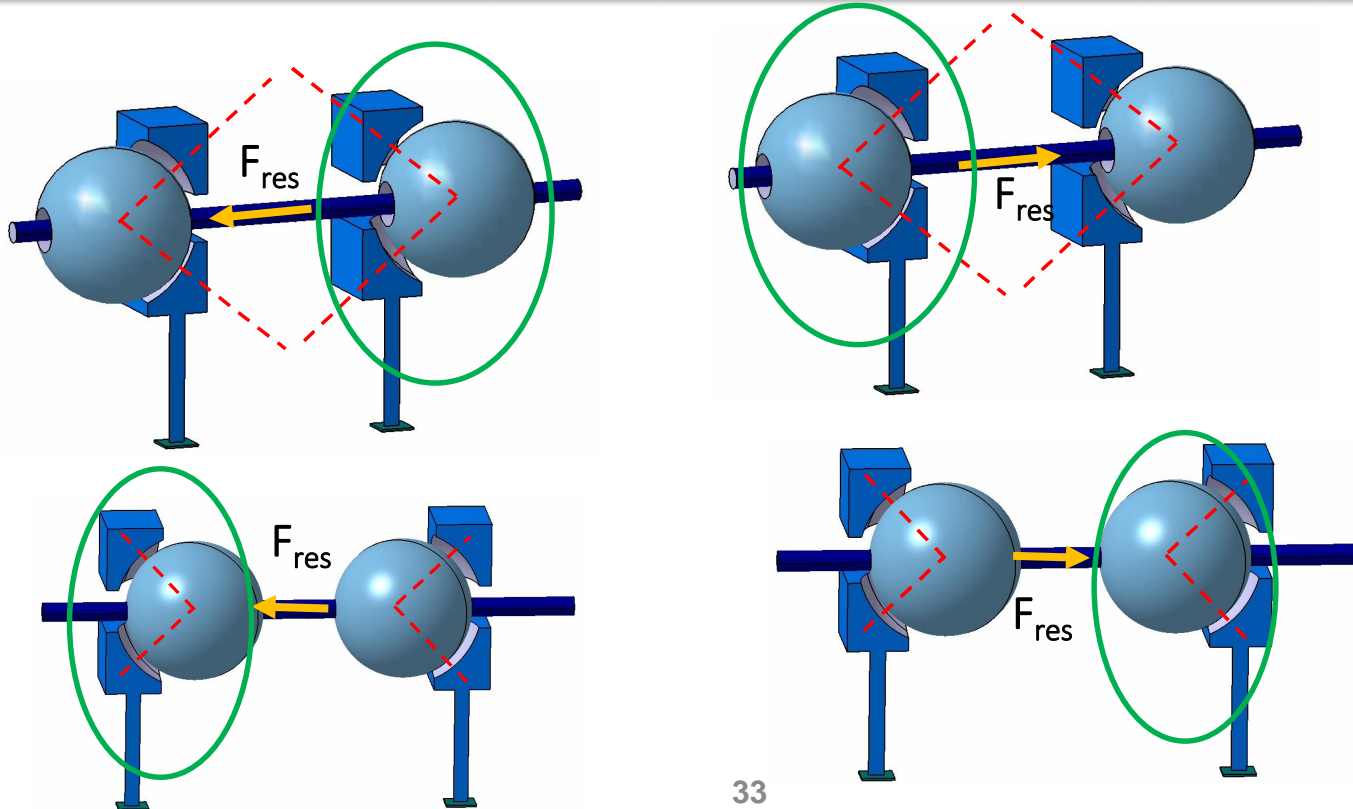
Calculate the norm of induced axial loads:

$$a_A = \frac{R_A}{2.Y_A} \quad a_B = \frac{R_B}{2.Y_B}$$

# Calculation of axial loads

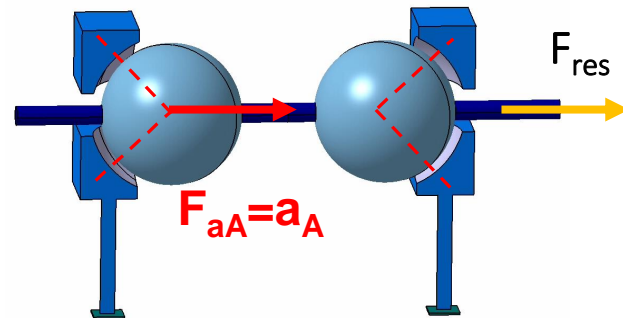
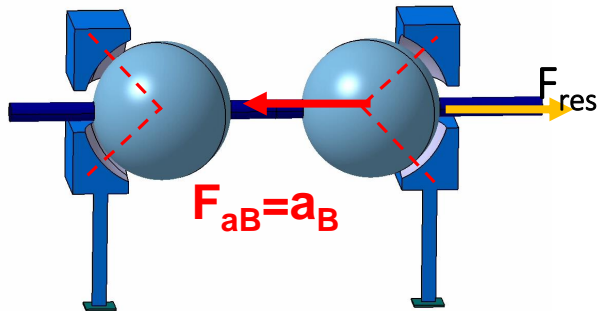
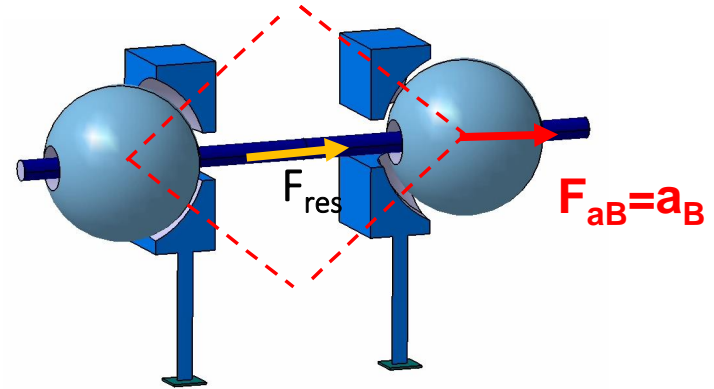
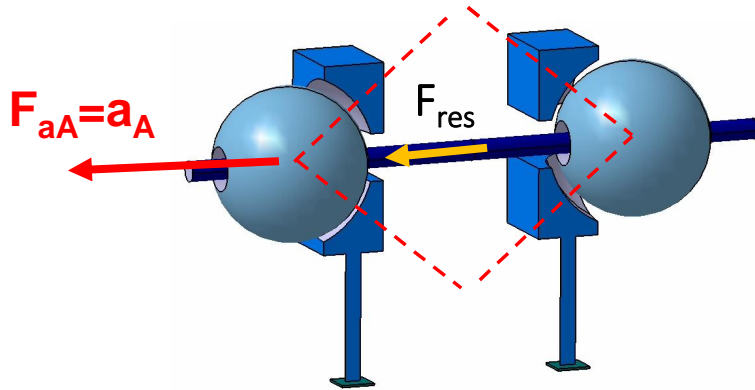
Determine the direction of the resultant axial load:  $\vec{F}_{res} = \vec{F}_a + \vec{a}_A + \vec{a}_B$

Determine the bearing that can support this load from the load direction



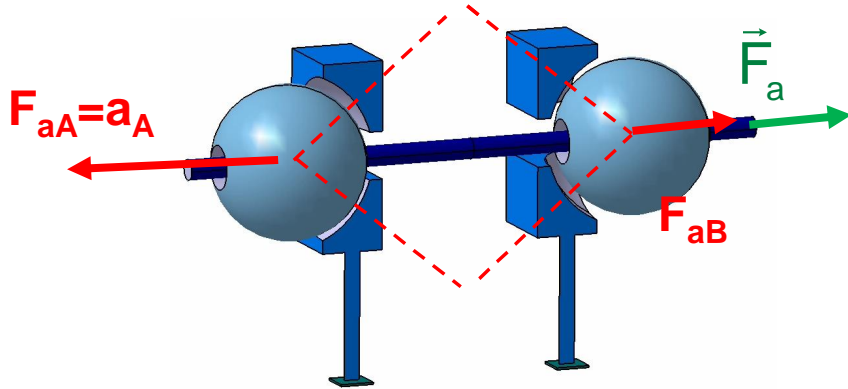
# Calculation of axial loads

The other bearing supports its induced axial load only.

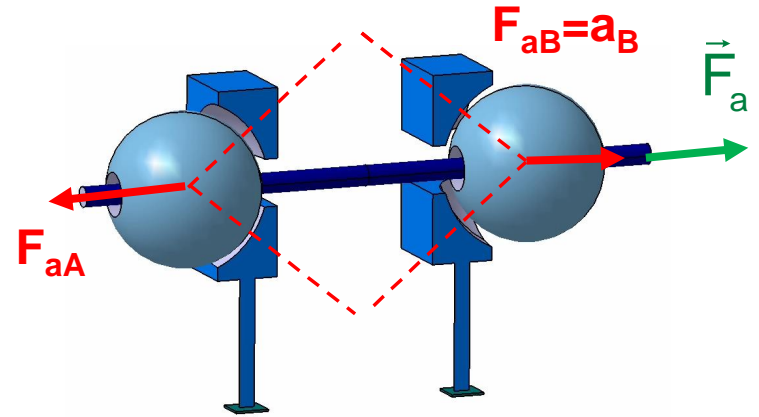


# Calculation of axial loads

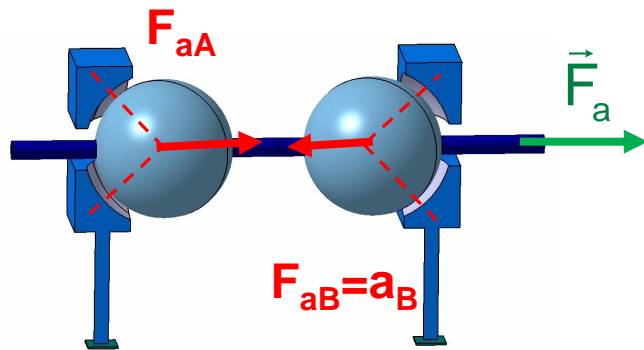
Write the axial equilibrium of the shaft



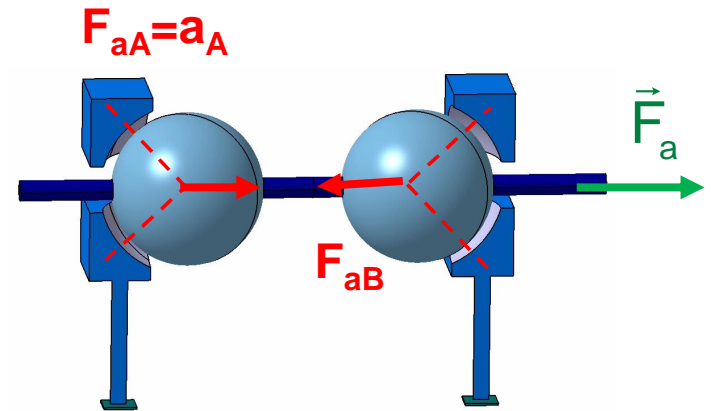
$$-a_A + F_{aB} + F_a = 0 \rightarrow F_{aB} = a_A - F_a$$



$$a_B - F_{aA} + \bar{F}_a = 0 \rightarrow F_{aA} = a_B + F_a$$



$$-a_B + F_{aA} + F_a = 0 \rightarrow F_{aA} = a_B - F_a$$

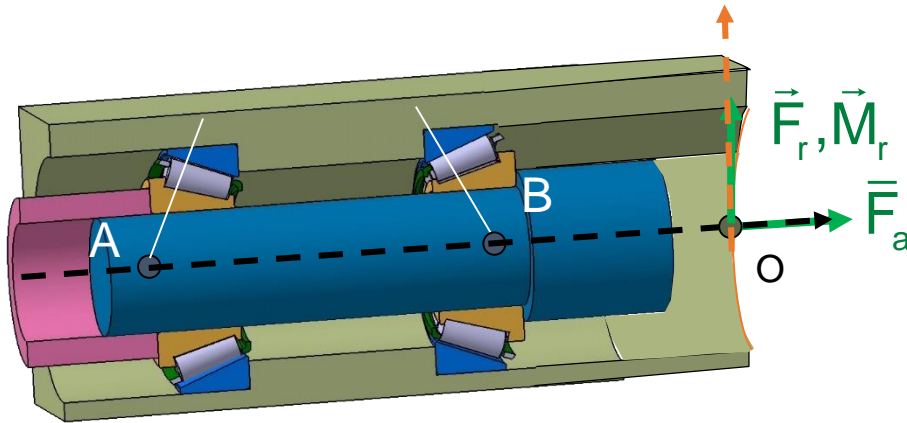


$$a_A - F_{aB} + \bar{F}_a = 0 \rightarrow F_{aB} = a_A + F_a$$



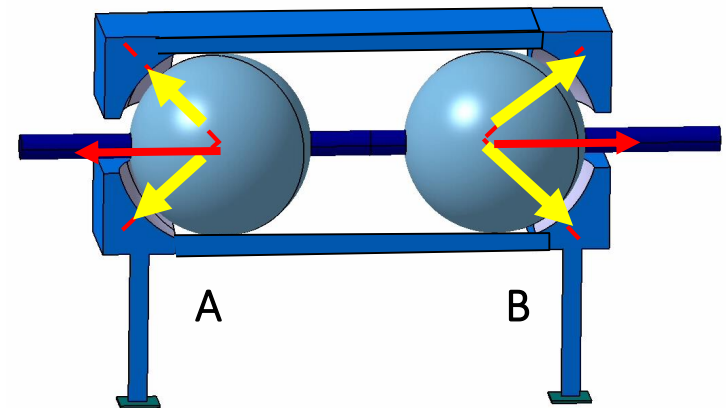
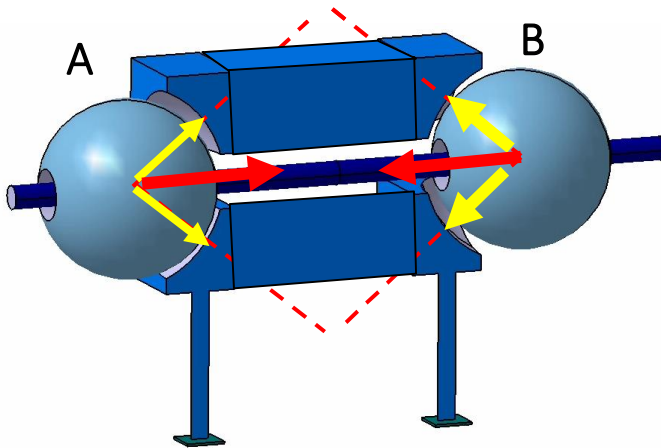
# Calculation of axial loads

Assuming external loads are on the housing



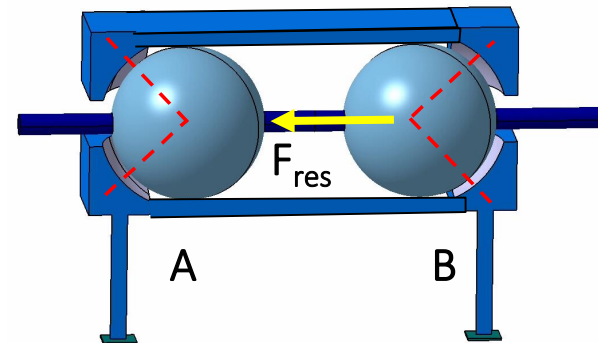
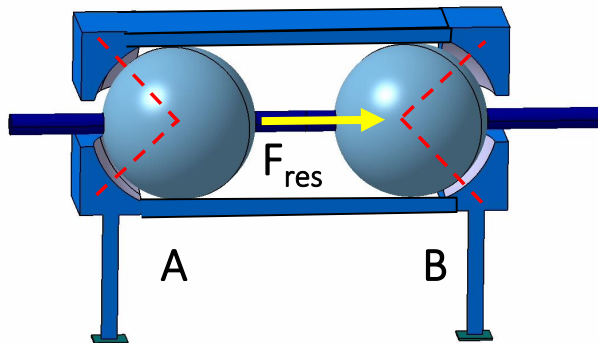
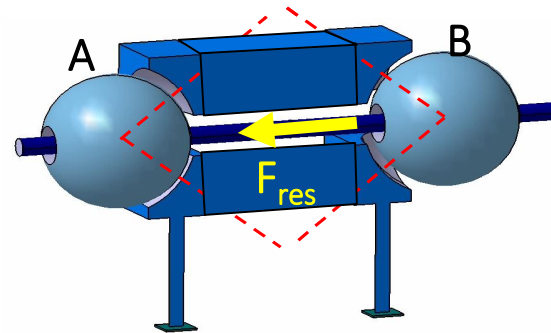
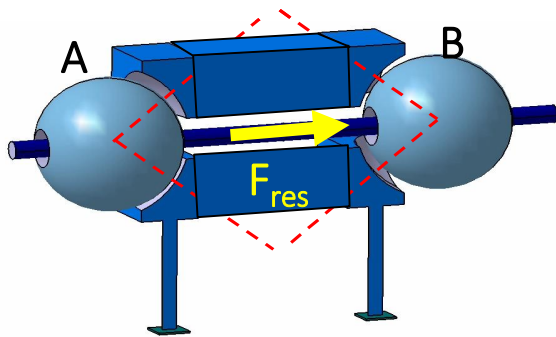
Identify external loads on the housing  
Locate the load centers

Identify the direction of the load exerted by the bearings on the housing



# Calculation of axial loads

Proceed the same way





**Take home message :**  
**One bearing supports its induced axial load.**  
**The other supports the external axial load**

## General method for angular contact bearing sizing

Static equilibrium helps determining axial and radial loads on each bearing.

Proceed as for radial bearings

1. Determine equivalent static bearing load  $P_0$ .

2. Check:  $C_0 > s_0 \times P_0$

where  $s_0$  depends on loading conditions and  $C_0$  is the static basic load rating,

3. Determine the equivalent dynamic bearing load  $P$   $P > P_{min}$

4. Check it is large enough

5. Calculate the bearing rating life:

$$L_{10} = \left( \frac{C}{P} \right)^n$$

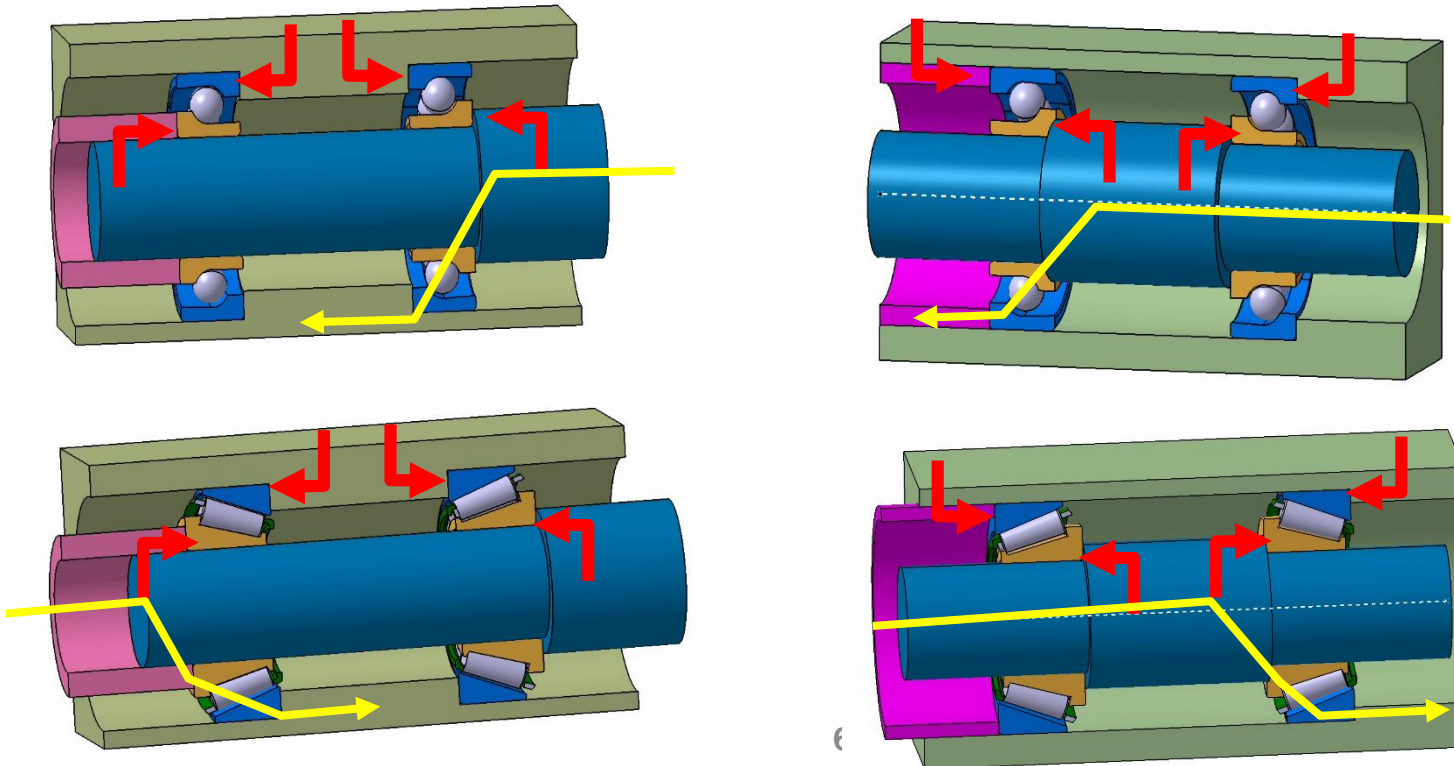


# **Mounting**

## **Clearance and preload**

## For angular bearing arrangements

- They are always by pairs
- Axial locating is done on 4 points which place is determined by arrangement type (X or O)



# Examples

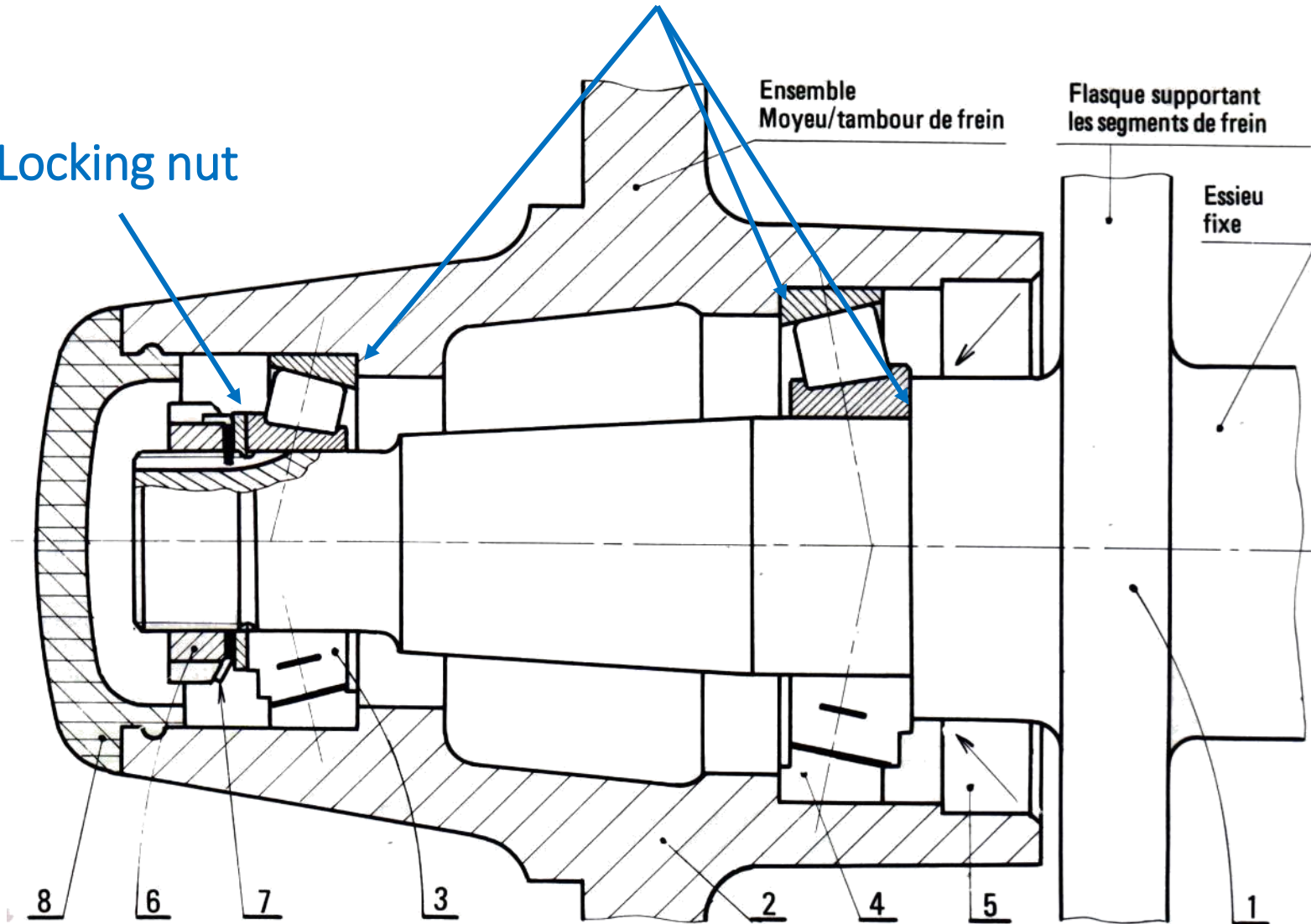
## Shoulders

Locking nut

Ensemble Moyeu/tambour de frein

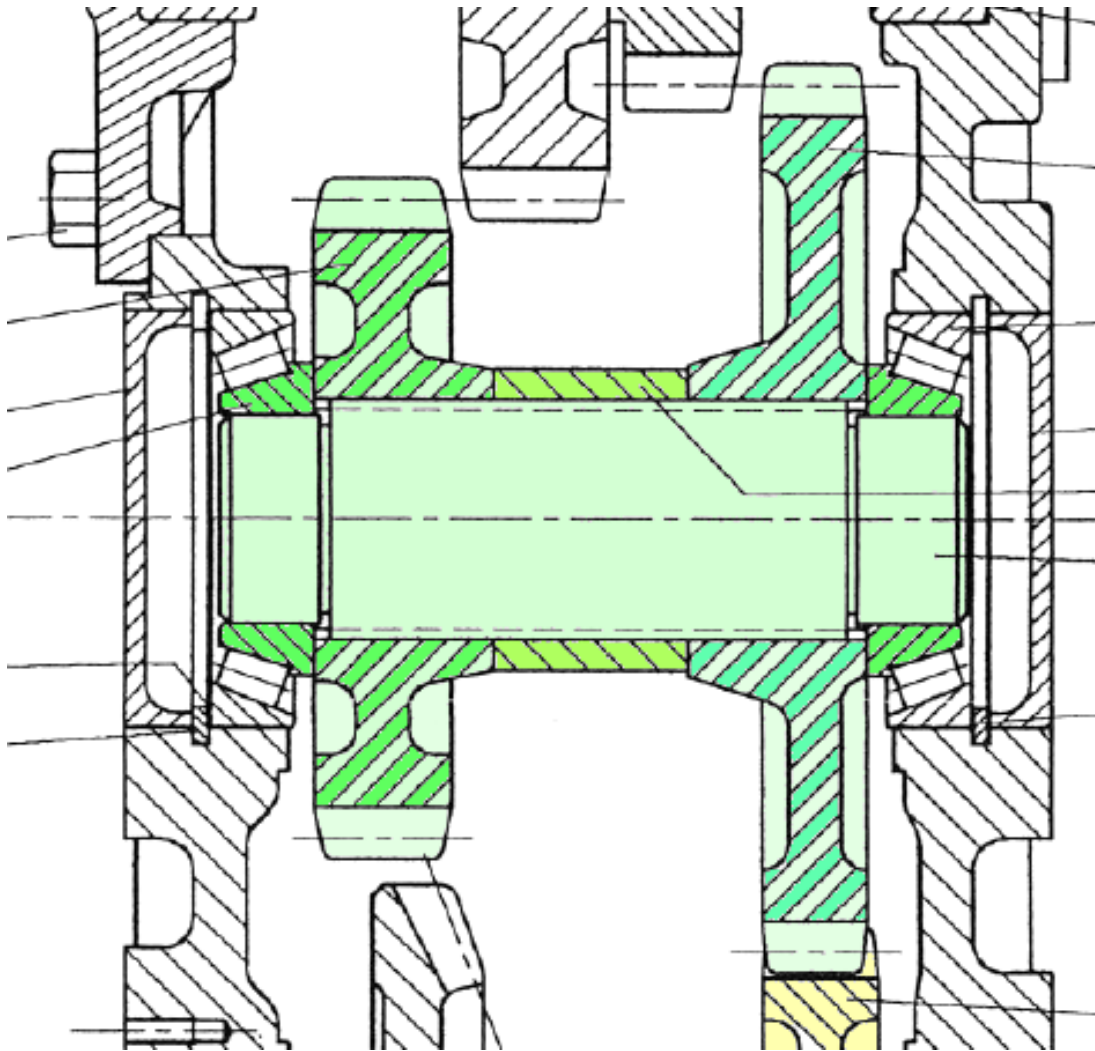
Flasque supportant les segments de frein

Essieu fixe



*Campervan wheel*

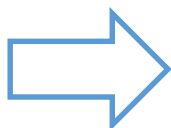
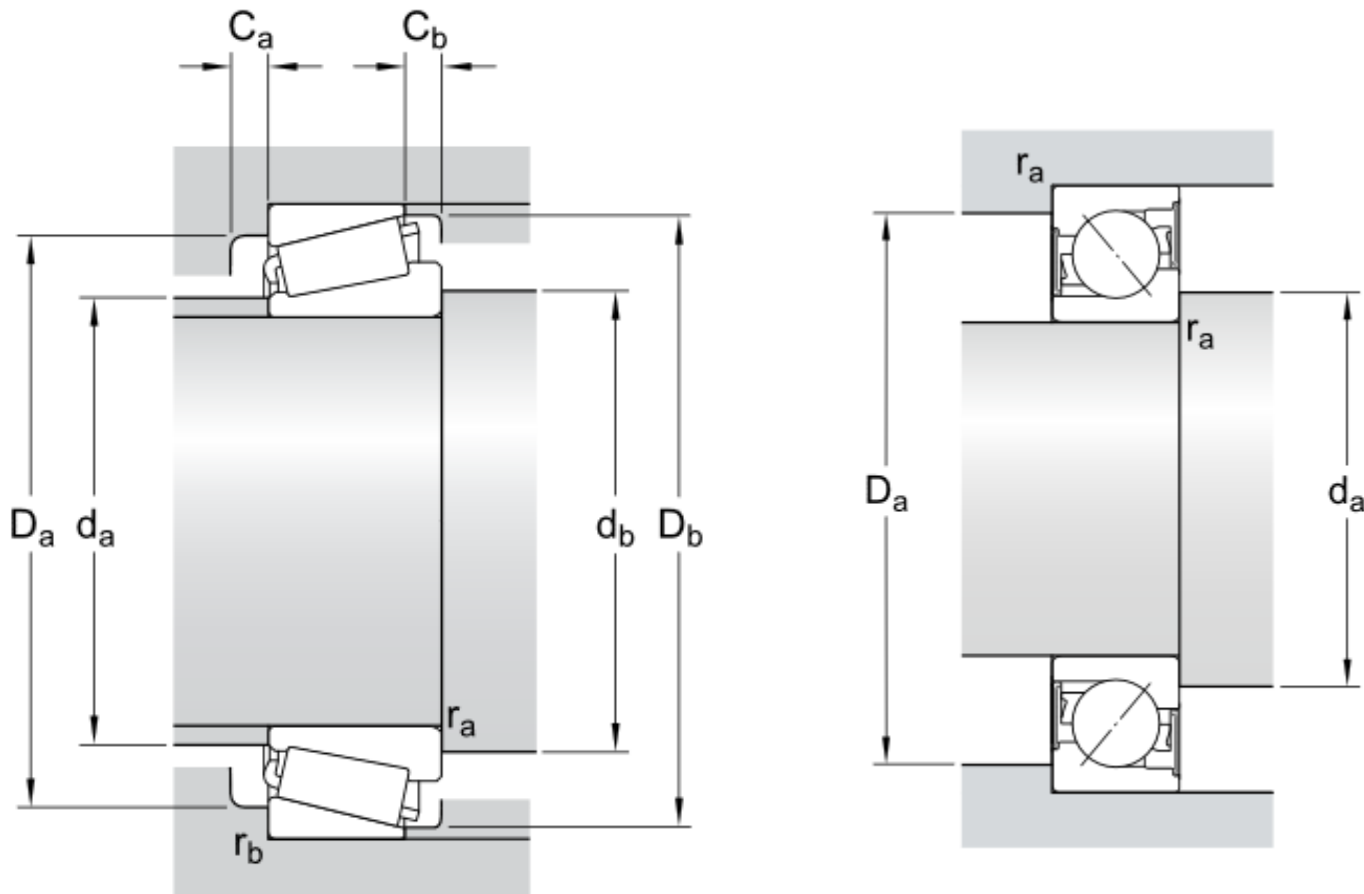
# Examples



<https://pierreprivot.wordpress.com/2008/01/23/sance-de-tp-du-23012008-g2/>



# Dimensions



Locating radial dimensions are provided by the manufacturer

## Preload

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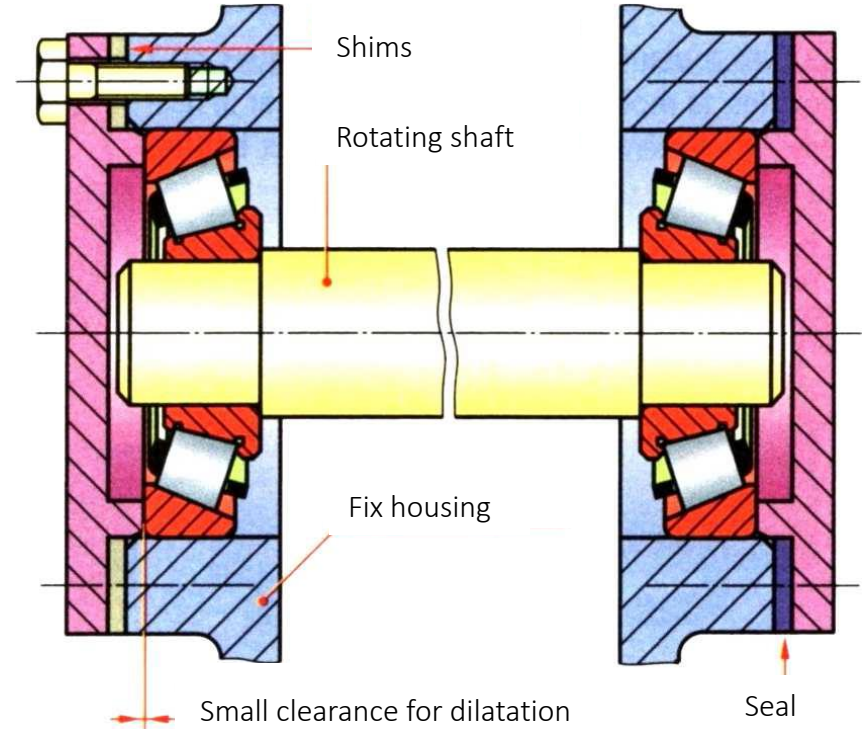
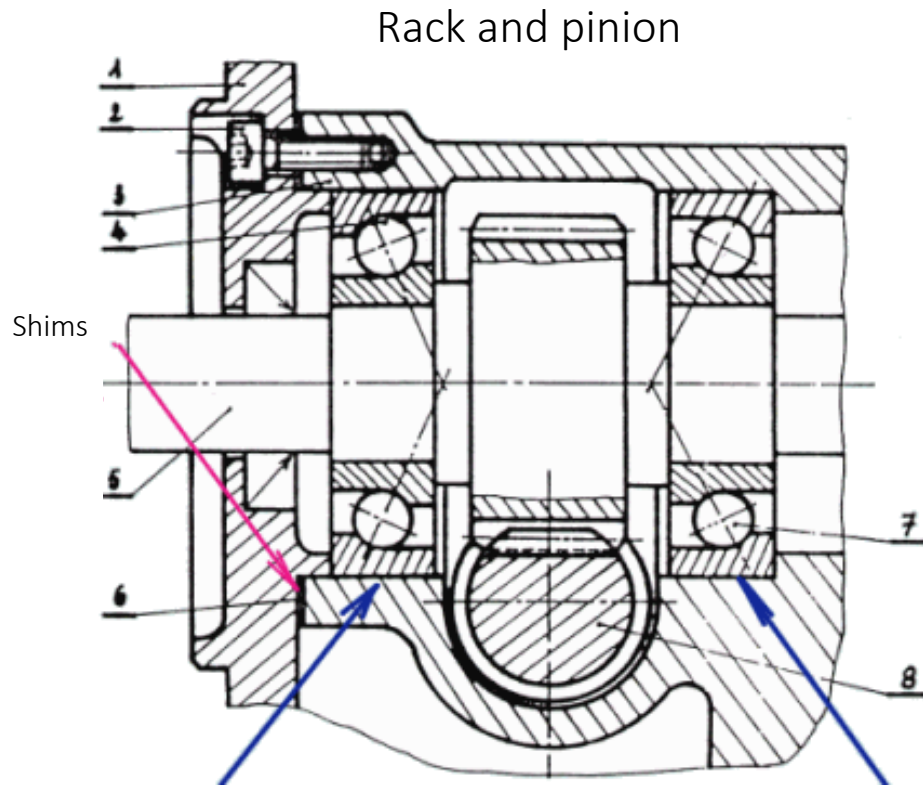
- Requires setting the axial fit by acting on the free ring

# Preload setting - examples



## Small shaft – fix load

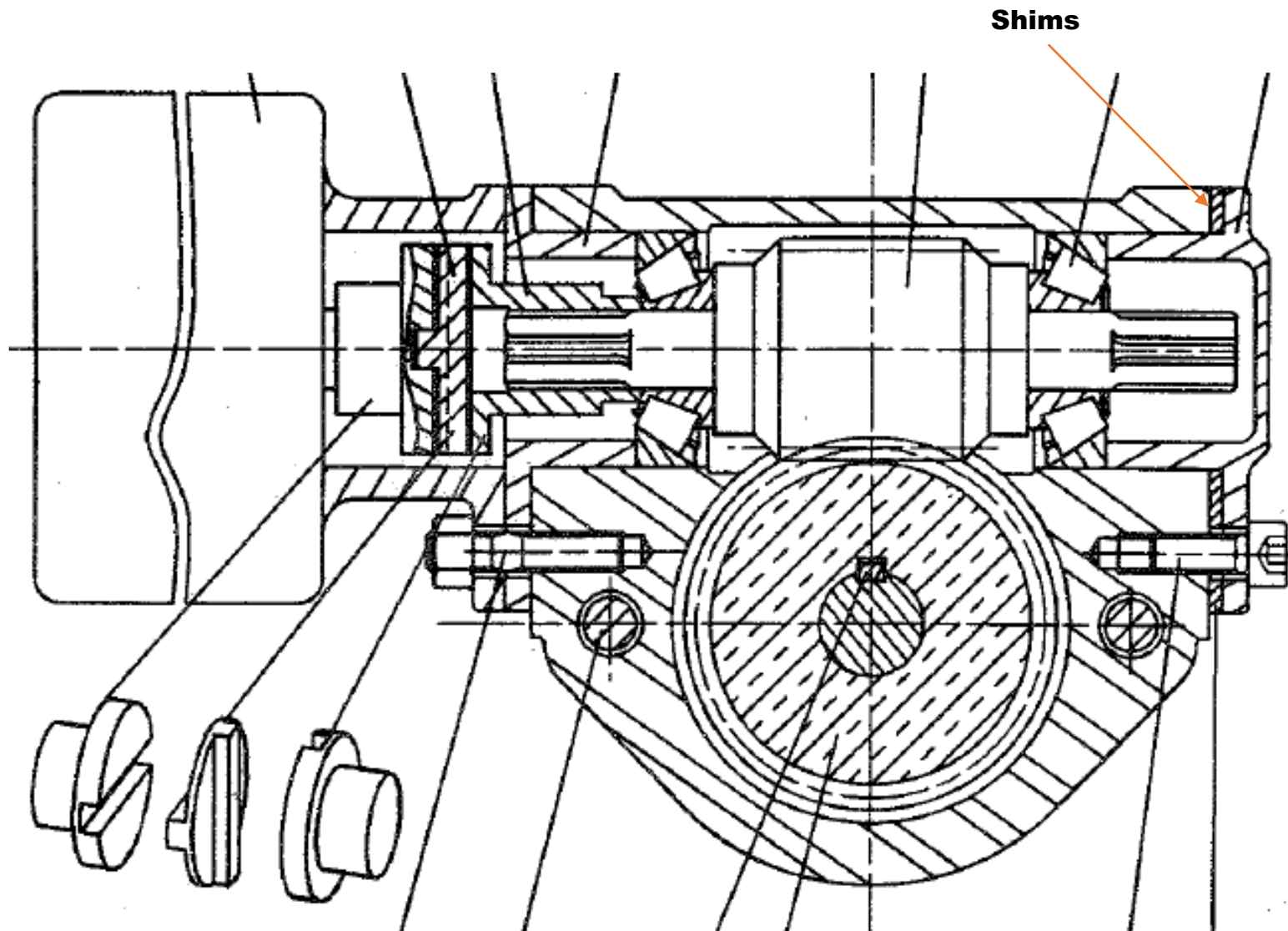
- Laminated shims



<http://joho.monsite.orange.fr/>

<http://barreau.matthieu.free.fr/cours/Liaison-pivot/pages/roulements-2.html>

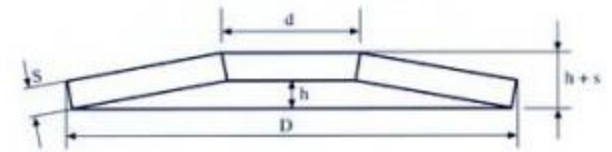
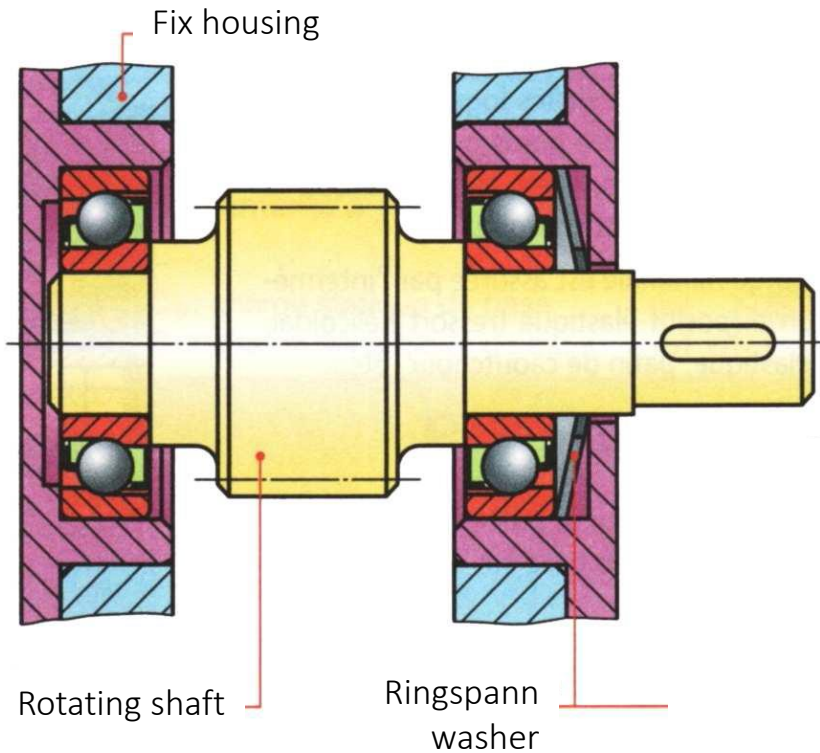
# Preload setting - examples



# Preload setting - examples

## Long shaft – Fix load

- Use springs: spring washer, Ringspann washer, etc.



Spring washer

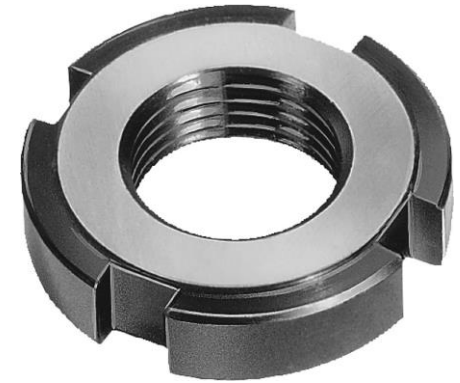
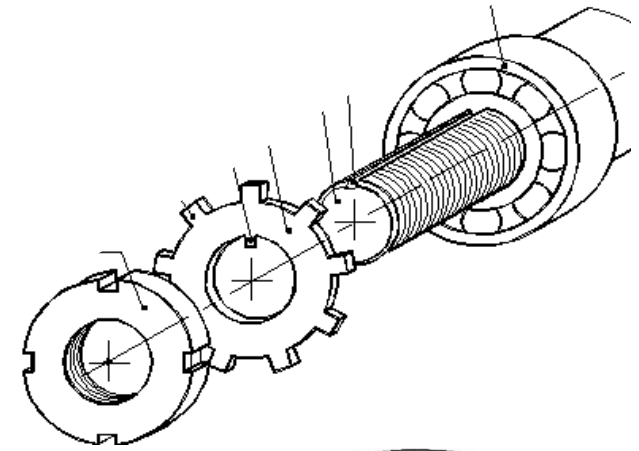


Ringspann washer membr de UNIVERSITÉ DE LYON

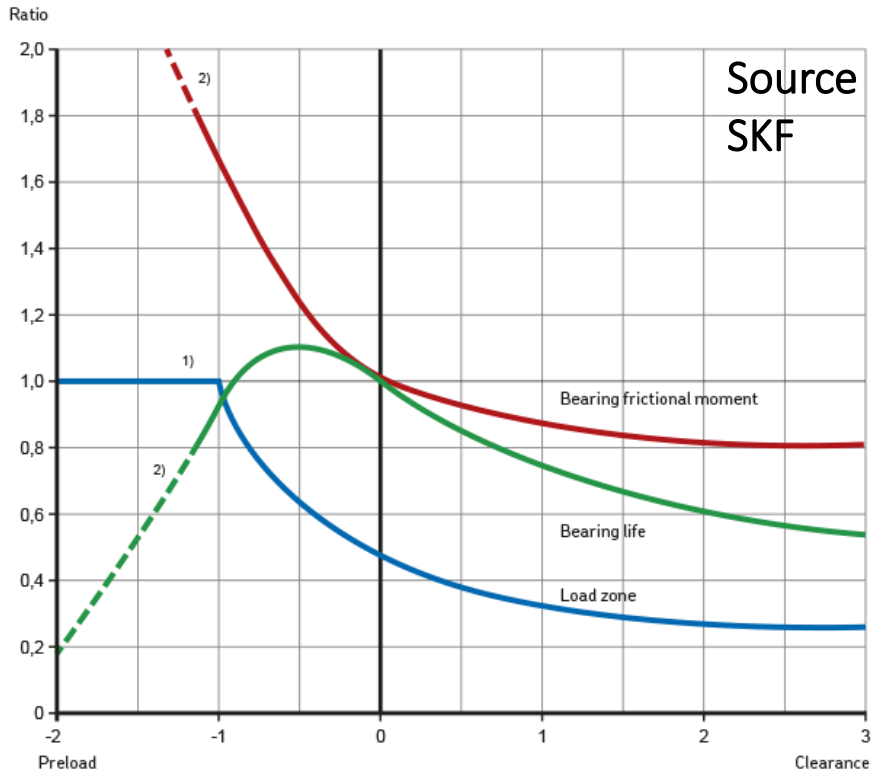
## Preload setting - examples

### Rotating housing – fix load

- Use a washer and a nut



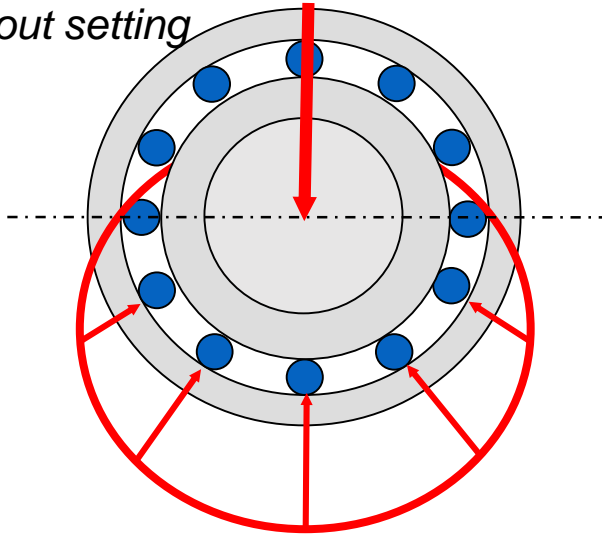
# Clearance or preload ?



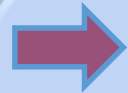
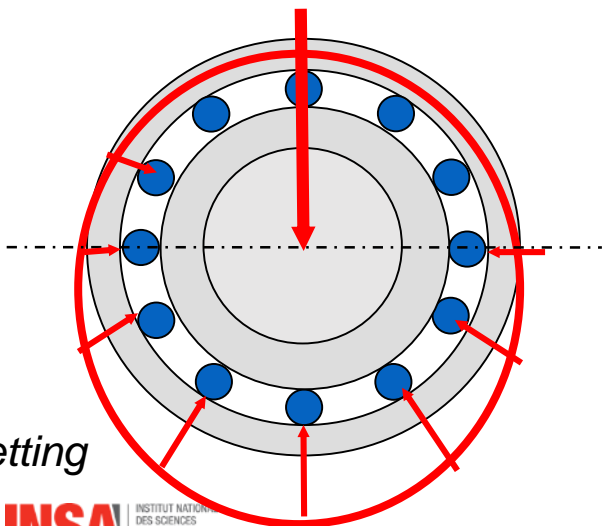
Clearance or preload is influenced by loading conditions: increase of temperature → dilatation, elasticity, etc

# Preload setting

*Without setting*



Distribution of the load  
on rolling elements



Better distribution of the load on rolling elements

- Better guiding of rolling elements  
→ less noise  
→ better shaft guiding
- Decreases chocks  
→ Increases rating life
- Increases arrangement stiffness  
→ Better shaft guiding

*With setting*